

Mining Astronomical Massive Data Sets

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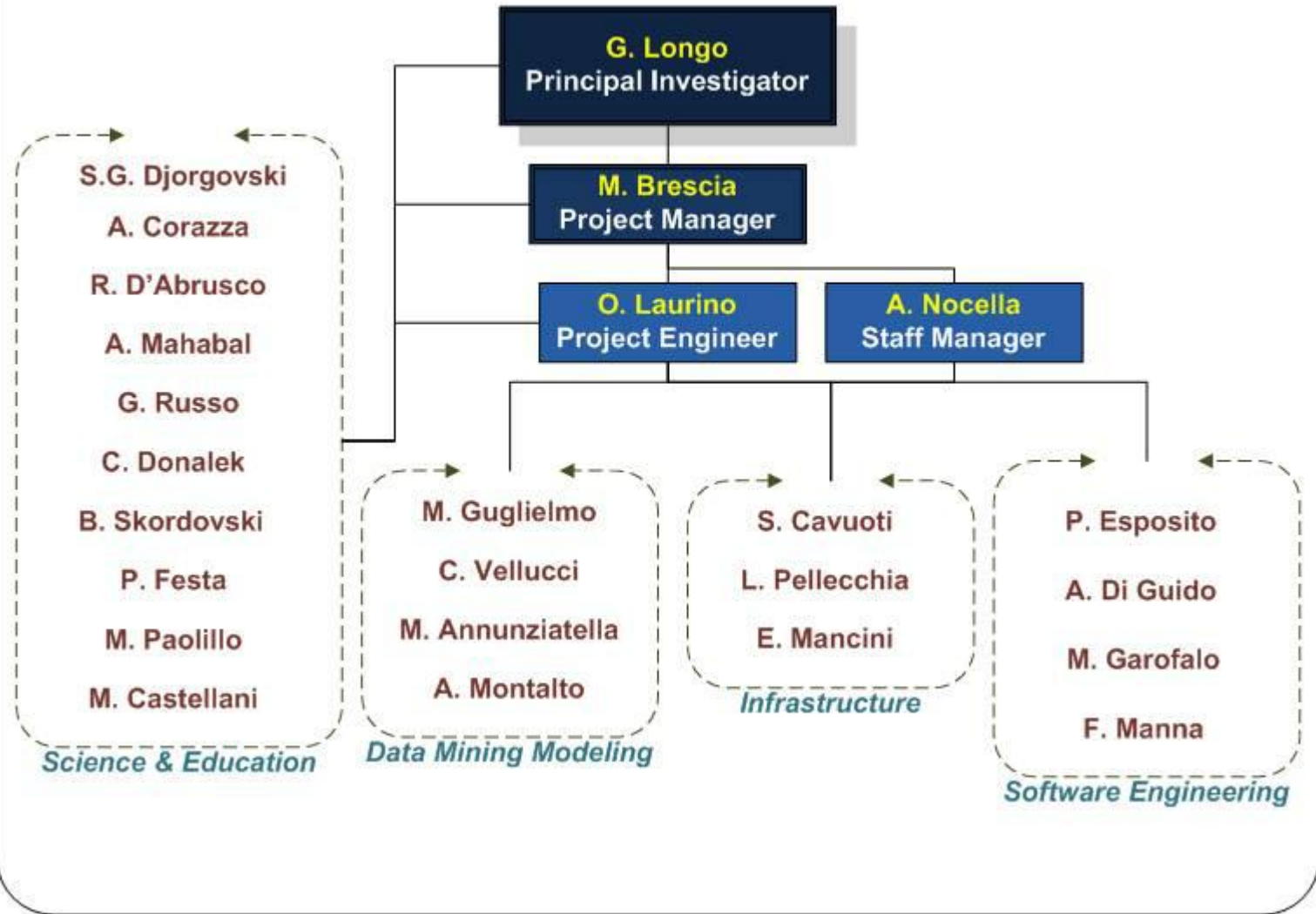


Summary

- methodological introduction on the problems posed by the data tsunami & why DM and SPR are a need !!
- some classification and clustering methods and their applications to some problems in observational cosmology
- possible applications in an evolving scenario



DAME ORGANIZATION CHART

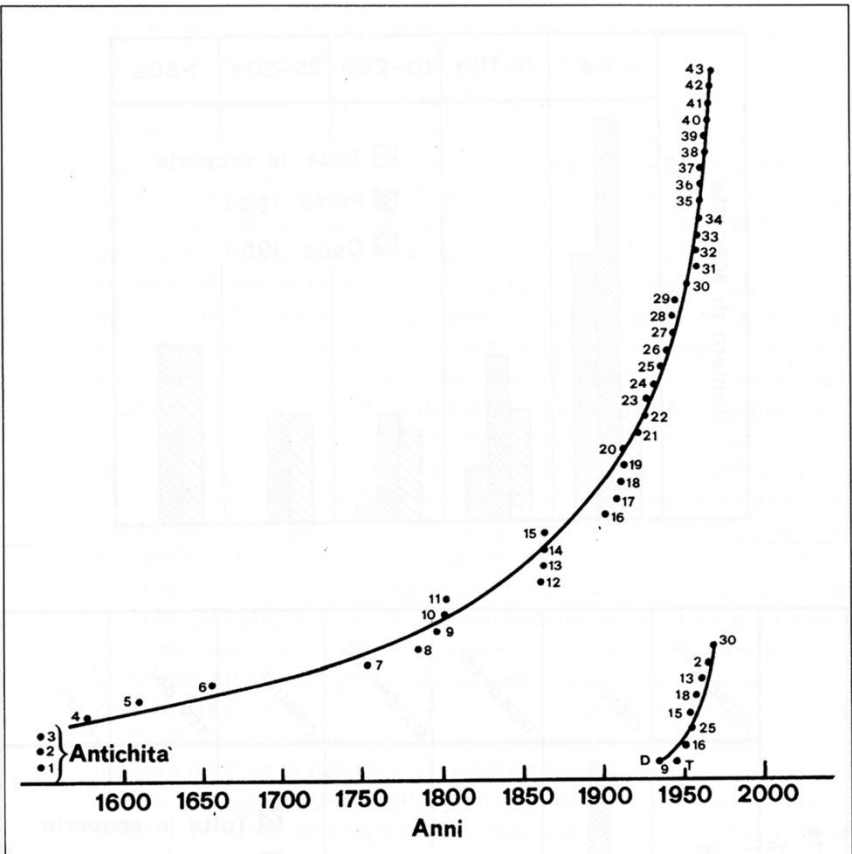


Summary

- methodological introduction on the problems posed by the data tsunami & why DM and SPR are a need !!
- some classification and clustering methods and their applications to two problems in observational cosmology (Photometric redshifts and QSO candidates identification)
- Future developments and possible applications in an evolving scenario



Part I – the scenario



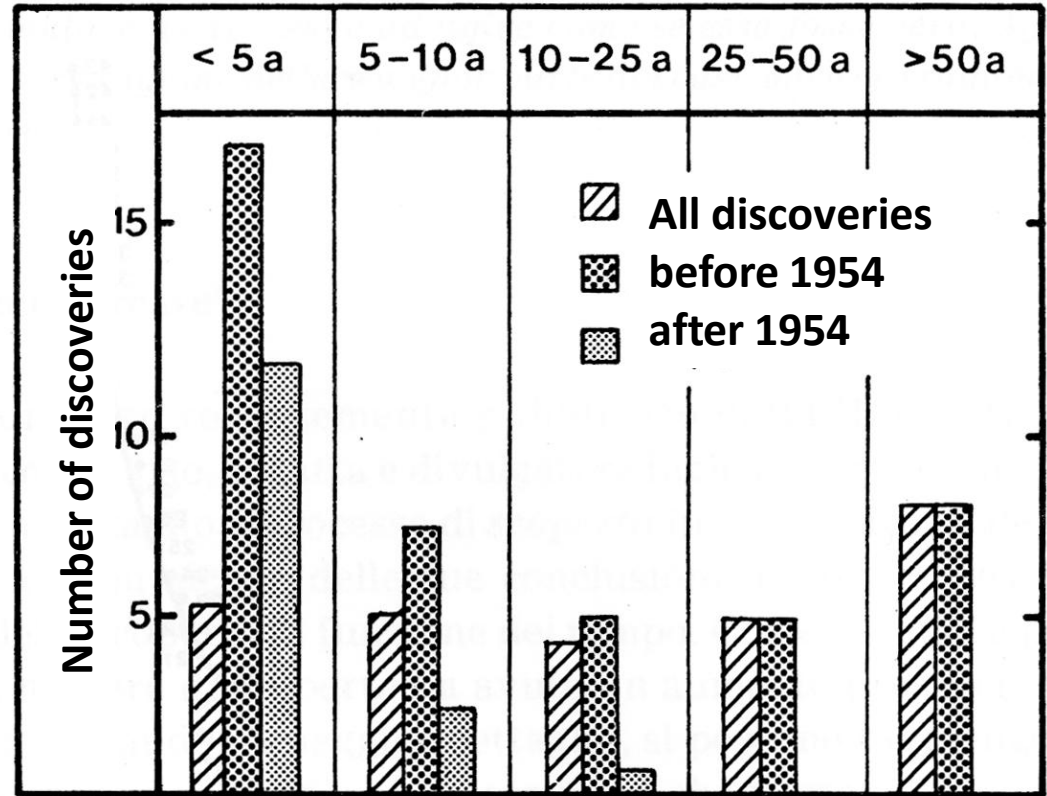
From M.Harwit, *Cosmic discoveries*

- | | |
|---------------------------|-----------------------------------|
| 1. Stars | 27. Radiogalaxies |
| 2. Planets | 28. Magnetic variables |
| 3. Novae | 29. Flare stars |
| 4. Comets | 30. Intergalactic magnetic fields |
| 5. Satellites | 31. X stars |
| 6. Rings | 32. X background |
| 7. Galactic clusters | 33. Quasar |
| 8. Galaxy clusters | 34. CMB |
| 9. Interplanetary dust | 35. Masers |
| 10. Asteroids | 36. Infrared stars |
| 11. Binary stars | 37. X galaxies |
| 12. Variable stars | 38. Pulsar |
| 13. Planetary nebulae | 39. Gamma background |
| 14. Globular clusters | 40. IR galaxies |
| 15. HII regions | 41. Superluminal sources |
| 16. Cold ISM | 42. GRB |
| 17. Giant stars | 43. Unidentified radio sources |
| 18. Cosmic rays | 44. ... |
| 19. Pulsating variables | 45. |
| 20. White dwarfs | |
| 21. Galaxies | |
| 22. Expansion of universe | |
| 23. Cosmic dust | |
| 24. Supernovae/novae | |
| 25. Gas in galaxies | |
| 26. SN remnants | |



The role of technology

Most discoveries take place immediately after a technological breakthrough



And now, the question is....
Where to search ...
for the next discoveries?

Next breakthrough will be in data fusion and access

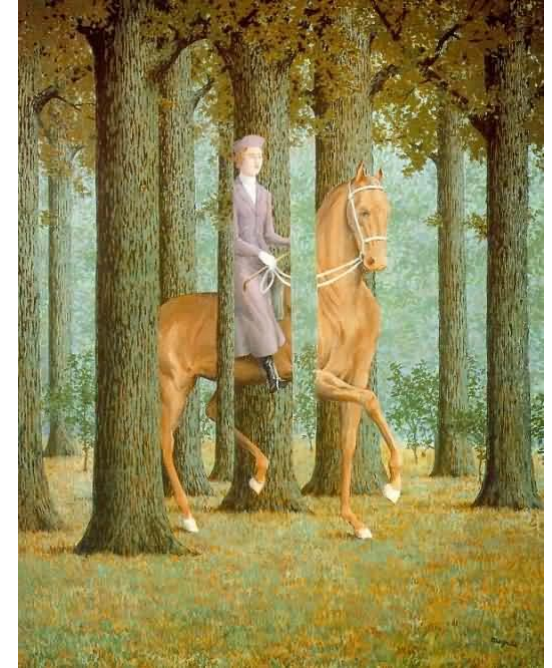
- We have **almost** reached the physical limit of observations (i.e. single photon counting) at **almost** all wavelength...
- Detectors are linear
- All electromagnetic bands have been opened...

Hence technological breakthrough can be in:

- **Accuracy** (lower flux limits, increased statistics)
- **Sampling** (angular resolution, time domain)
- **Complexity** (data fusion, data mining, modeling, etc.)

New insights will depend mainly on:

- Capability to ACCESS AND MERGE heterogeneous information (multi-epoch, multi- λ , etc.)
- Capability to recognize patterns or trends in the parameter space (i.e. physical laws) which are not limited to the human 3-D visualization
- Capability to extract patterns from very large multiwavelength, multiepoch multi-technique parameter spaces





The parameter space

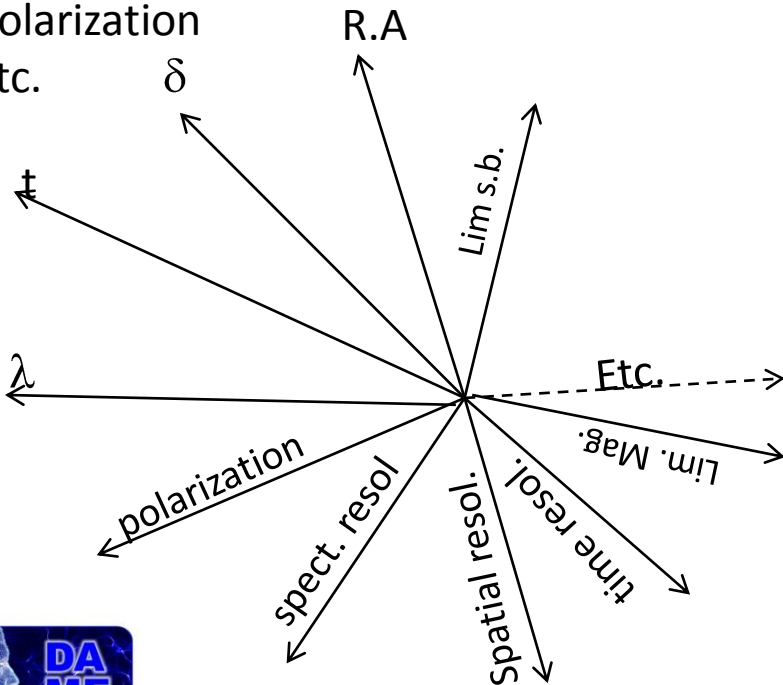
Any observed (simulated) datum p defines a point (region) in a subset of \mathbb{R}^N . Es:

- RA and dec
- time
- λ
- experimental setup (spatial and spectral resolution, limiting mag, limiting surface brightness, etc.) parameters
- fluxes
- polarization
- Etc.

$$p \in \mathfrak{R}^N \quad N \gg 100$$

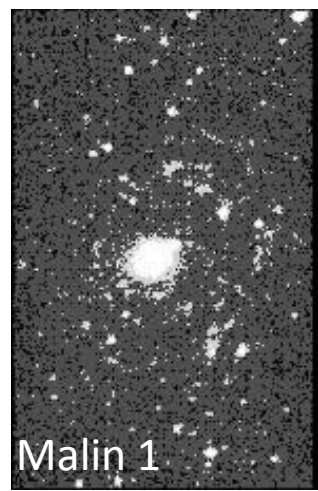
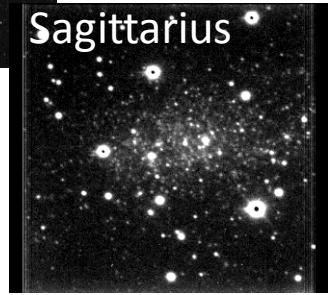
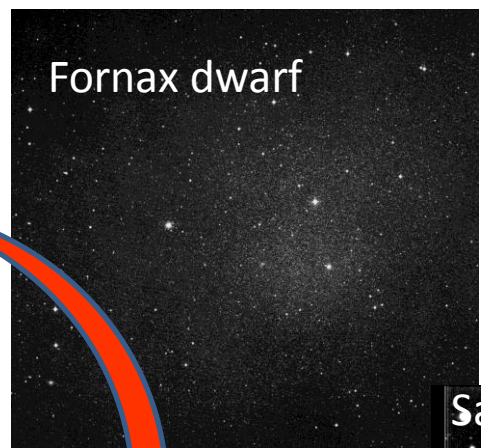
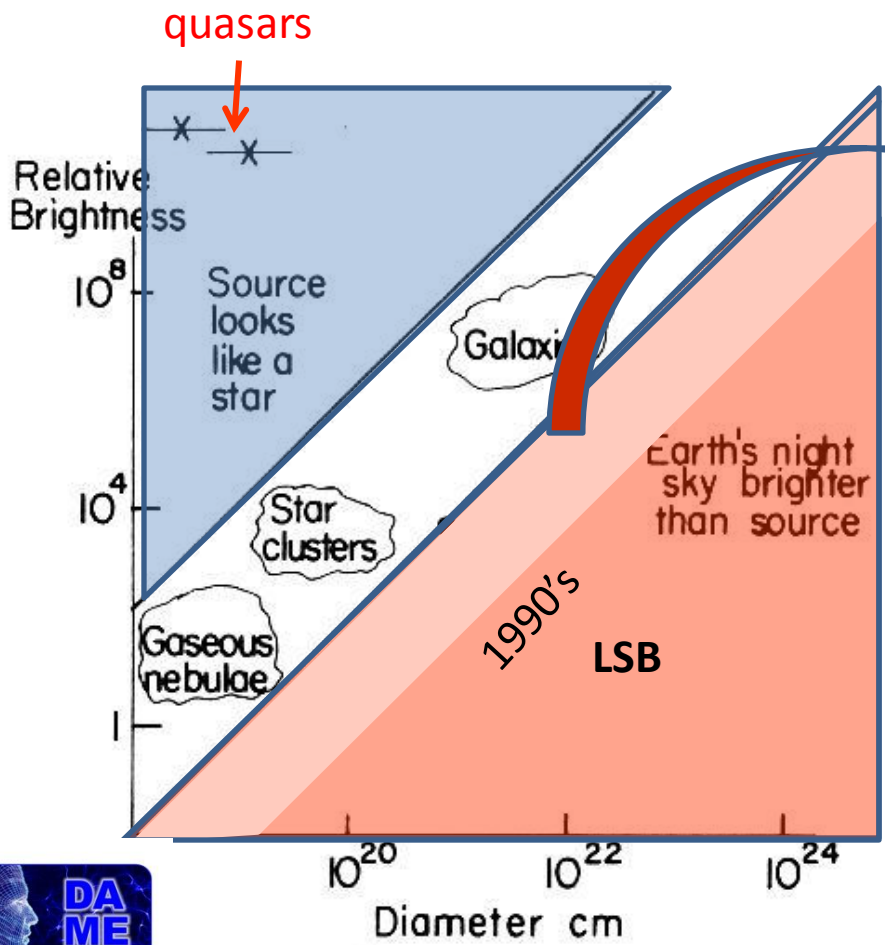
The parameter space concept is crucial to:

1. Guide the quest for new discoveries (observations can be guided to explore poorly known regions), ...
2. Find new physical laws (patterns)
3. Etc,



Every time you improve the coverage of the PS....

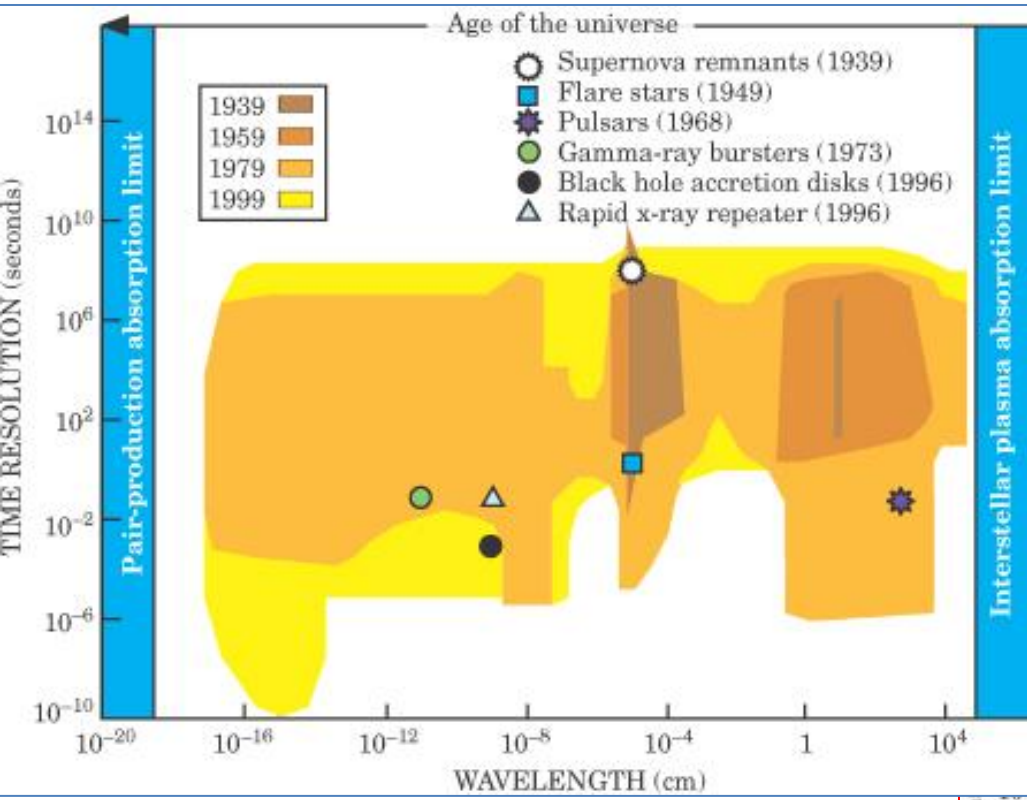
Every time a new technology enlarges the parameter space or allows a better sampling of it, new discoveries are bound to take place



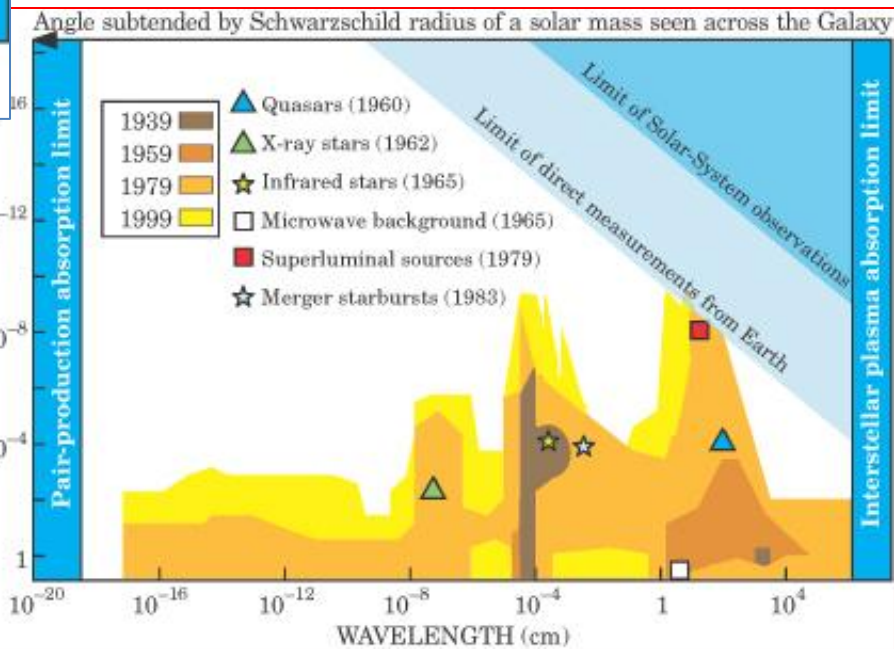
Discovery of Low surface brightness Universe



Improving coverage of the Parameter space - II



Projection of parameter space along (time resolution & wavelength)



Projection of parameter space along (angular resolution & wavelength)



Calibrated data

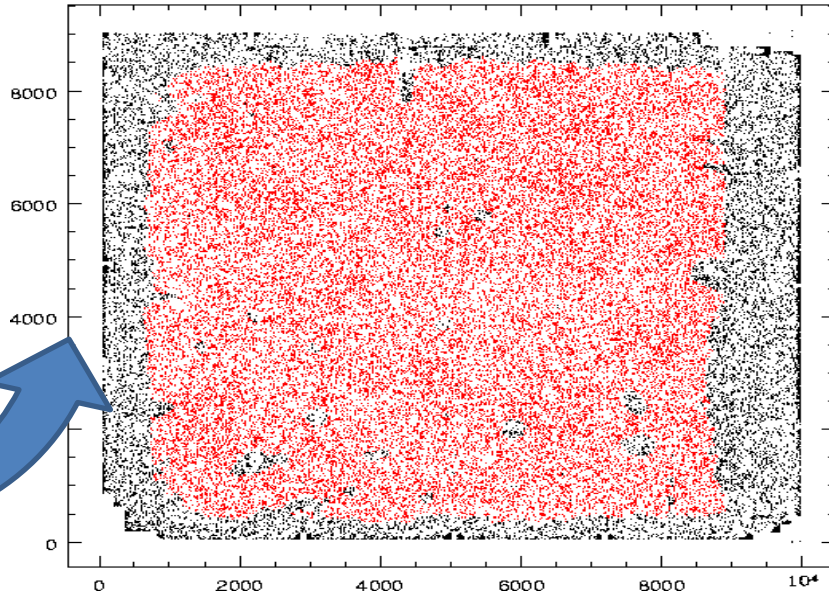
30 arcmin

1/160.000 of the sky, moderately deep (25.0 in r)

55.000 detected sources (0.75 mag above m lim)



CDF 2 R



$p = \{ \text{isophotal, petrosian, aperture magnitudes, concentration indexes, shape parameters, etc.} \}$

$$p^1 = \{ R^1, \delta^1, t, \lambda, \Delta\lambda_1, f_1^{1,1}, \Delta f_1^{1,1}, \dots, f_1^{1,m}, \Delta f_1^{1,m} \}, \{ \lambda_n, \Delta\lambda_n, f_n^{1,1}, \Delta f_n^{1,1}, \dots, f_n^{1,m}, \Delta f_n^{1,m} \}$$

$$p^2 = \{ R^2, \delta^2, t, \lambda, \Delta\lambda_1, f_1^{2,1}, \Delta f_1^{2,1}, \dots, f_1^{2,m}, \Delta f_1^{2,m} \}, \{ \lambda_n, \Delta\lambda_n, f_n^{2,1}, \Delta f_n^{2,1}, \dots, f_n^{2,m}, \Delta f_n^{2,m} \}$$

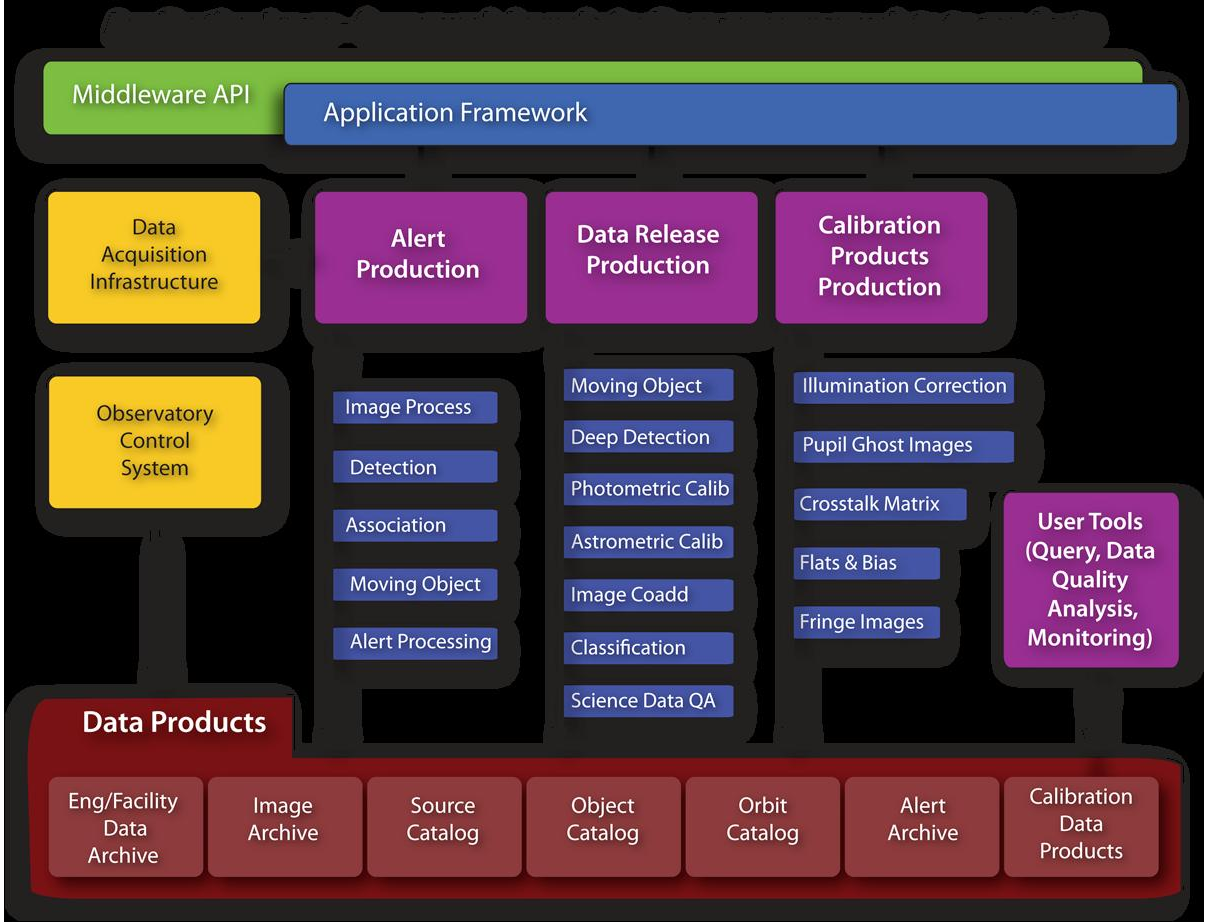
.....

$$p^N = \{ R^N, \delta^N, t, \lambda, \Delta\lambda_1, f_1^{N,1}, \Delta f_1^{N,1}, \dots, f_1^{N,m}, \Delta f_1^{N,m} \}, \{ \lambda_n, \Delta\lambda_n, f_n^{N,1}, \Delta f_n^{N,1}, \dots, f_n^{N,m}, \Delta f_n^{N,m} \}$$

$$D = 3 + m \times n$$

$N > 10^9, D \gg 100, i \gg 10$

Computational (HW+SW) challenges: LSST



Per Night

- 15 TB of images
- 1 TB catalogs
- 60 sec alerts for 10^5 - 10^6 Objects

Per Year

- 6.5 PB per year of images and catalogs

Lifetime

- 10 B Stars and 10 B Galaxies
- 60-70 PB of images

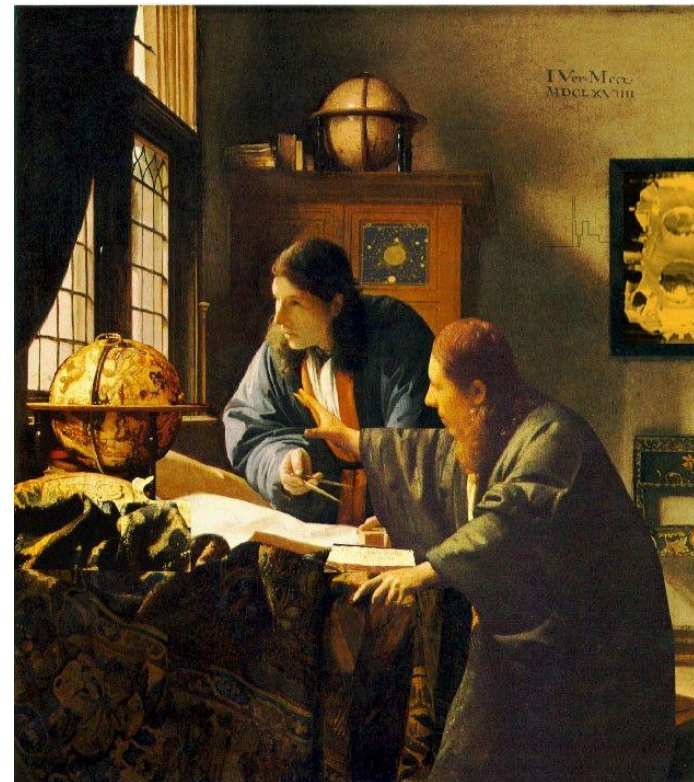


Part II

DATA MINING IN ASTRONOMY

We would all testify to the growing gap between the generation of data and our *understanding* of it ...

Ian H. Witten & E. Frank, Data Mining, 2001





The astrophysics domain

Data Gathering (e.g., new generation instruments ...)

→ **Data Farming:**

Storage/Archiving
Indexing, Searchability
Data Fusion, Interoperability, ontologies, etc.

Data storage , Pbytes
Data access $>10^3$ access

→ **Data Mining** (or Knowledge Discovery in Databases):

Pattern or correlation search
Clustering analysis, automated classification
Outlier / anomaly searches
Hyperdimensional visualization

→ **Data visualization and understanding**

Computer aided understanding
KDD
Etc.

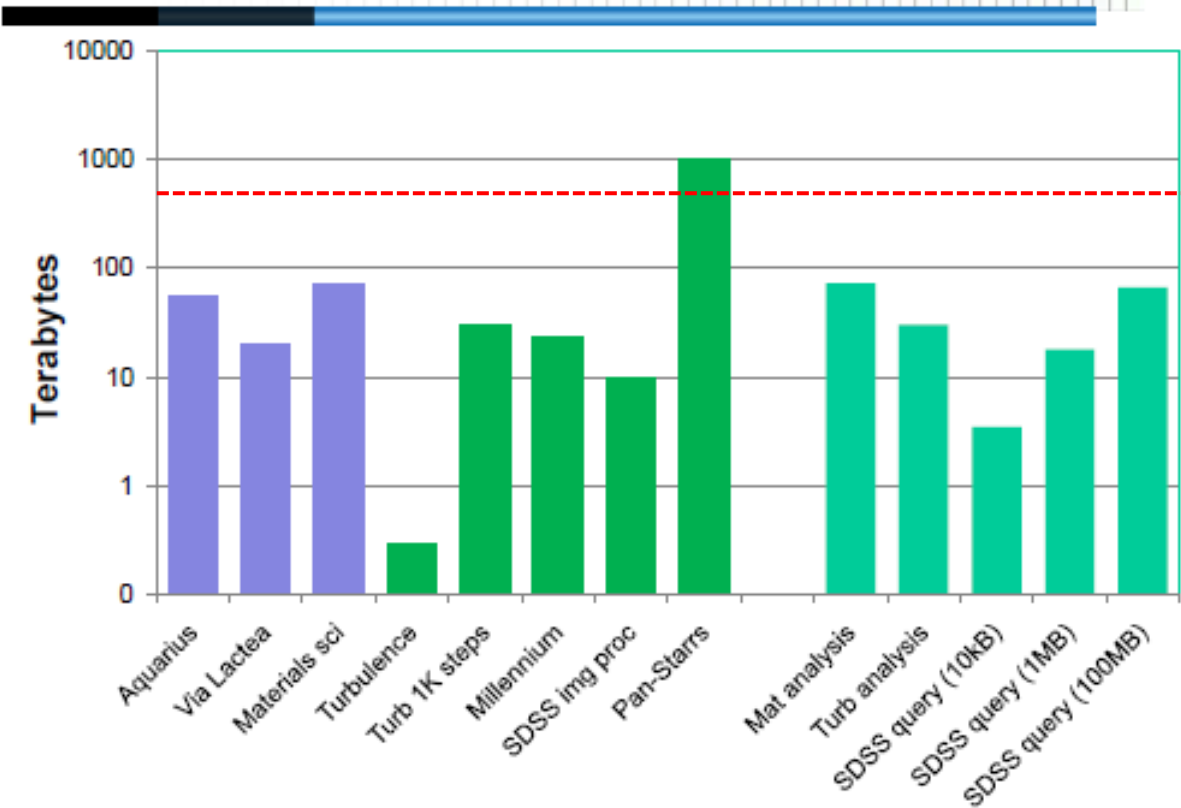
Scalability: Petaflops, Exaflops
Computing power (multicore)
Algorithm: parallelism
Visualization: N-dimensional

→ **New Knowledge**



Data storage (problem to be solved)

The Data Sizes Involved



Memory of Today's Biggest System

Elaboration needs to take place where the data are

From Alex Szalay, "Amdahl's Law and Extreme Data-Intensive Computing," 2010 Salishan Conf. on High Speed Computing

Expected growth rates can exceed 1 PB/year for Raw Data - LSST may reach 100 PB!



Donald Rumsfeld's explanation of data mining (but he did not know...)

*There are known knowns,
There are known unknowns, and
There are unknown unknowns*

Classification

Morphological classification of galaxies
Star/galaxy separation, etc.

Regression

Photometric redshifts

Clustering

Search for peculiar and rare objects,
Etc.

Donald Rumsfeld's
about Iraqi war



Scalability of most relevant astronomical algorithms

- **Querying:** spherical range-search $O(N)$, orthogonal range-search $O(N)$, spatial join $O(N^2)$, nearest-neighbor $O(N)$, all-nearest-neighbors $O(N^2)$
- **Density estimation:** mixture of Gaussians, kernel density estimation $O(N^2)$, kernel conditional density estimation $O(N^3)$
- **Regression:** linear regression, kernel regression $O(N^2)$, Gaussian process regression $O(N^3)$
- **Classification:** decision tree, nearest-neighbor classifier $O(N^2)$, nonparametric Bayes classifier $O(N^2)$, support vector machine $O(N^3)$
- **Dimension reduction:** principal component analysis, non-negative matrix factorization, kernel PCA $O(N^3)$, maximum variance unfolding $O(N^3)$
- **Outlier detection:** by density estimation or dimension reduction
- **Clustering:** by density estimation or dimension reduction, k-means, meanshift segmentation $O(N^2)$, hierarchical (FoF) clustering $O(N^3)$
- **Time series analysis:** Kalman filter, hidden Markov model, trajectory tracking $O(N^n)$
- **Feature selection and causality:** LASSO, L1 SVM, Gaussian graphical models, discrete graphical models
- **2-sample testing and testing and matching:** bipartite matching $O(N^3)$, n-point correlation $O(N^n)$

Brute force is not a solution

Exascale (needed for crosscorrelation on archives like LSST: Exascale = *1,000X capability of Today*)

- **Exascale != Exaflops but**

Exascale at the data center size => *Exaflops*

Exascale at the “rack” size => *Petaflops for departmental systems*

Exascale embedded => *Teraflops in a cube*

It took 14+ years to get from

1st Petaflops workshop: 1994, thru NSF studies, HTMT, HPCS ... to give us to Petaflops *in 2009*



***We should be OVERJOYED if all
You need is:***

- ***JUST a Million cores***
- ***ONLY 1 Nuclear Power Plant***
- ***MINIMAL programming support***

Better algorithms are needed

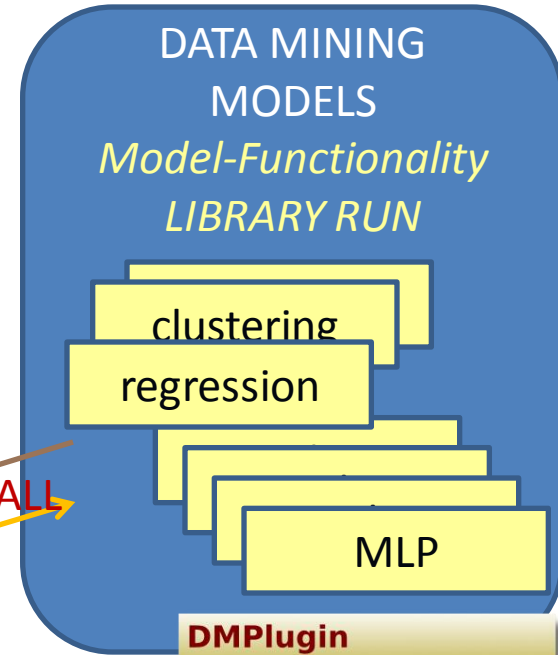
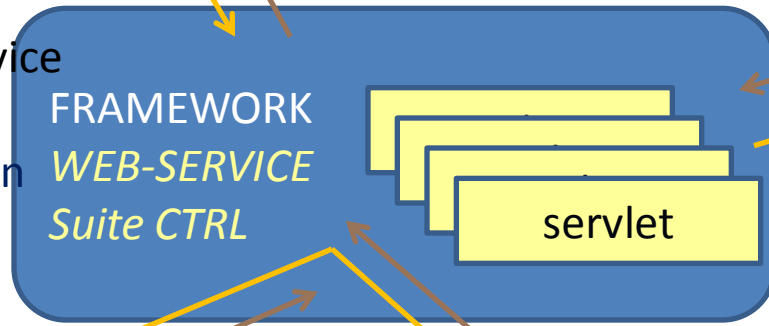
The DAME architecture



user



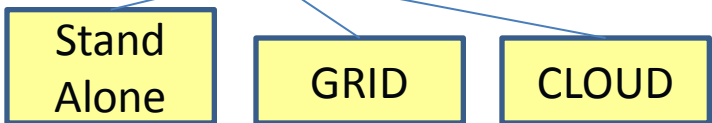
Client-server AJAX
(Asynchronous Java-
Xml) based;
interactive web app
based on Javascript
(GWT-EXT);



HW env virtualization;
Storage + Execution LIB
Data format conversion

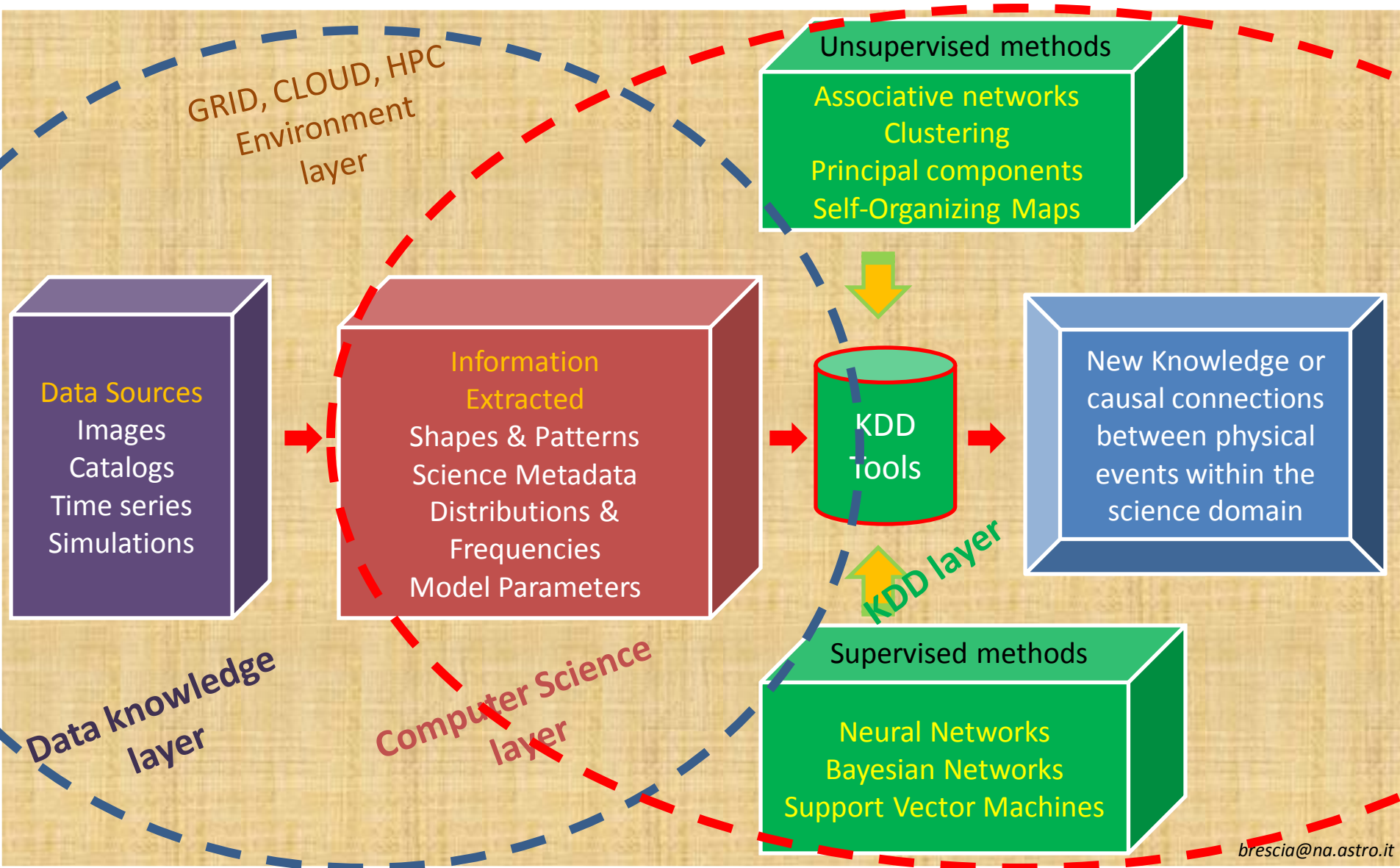


Restful, Stateless Web Service
experiment data, working
flow trigger and supervision
Servlets based on XML
protocol



Vobs standards and infrastructure

Data mining level



What is DAME



DAME is a joint effort between University Federico II, INAF-OACN, and Caltech aimed at implementing (as web application) a scientific gateway for data analysis, exploration, mining and visualization tools, on top of virtualized distributed computing environment.

<http://voneural.na.infn.it/>

Technical and management info
Documents
Science cases
Newsletter

The screenshot shows the DAME website home page. At the top, there is a navigation bar with links for Home, Project Documents, Download, and Contact Us. The main header features the 'DAta Mining & Exploration' logo and the 'DAME' acronym. Below this, the text reads 'Data Mining & Exploration Project'. The page is divided into several sections: 'News & Events' with links to 'New DAME Prototype released', 'DAME Lecture @ IPAC-09', and 'DAME @ IACAROS Conference'; 'Partners' listing institutions like 'Dipartimento di Fisica (sezione di Astronomia) - Università degli Studi di Napoli Federico II'; 'Related links' including 'VOTECH (Virtual Observatory Technological Infrastructures)', 'S.Co.P.E. (High Performance distributed Cooperative System for scientific Experiment)', and 'INAF - Osservatorio Astronomico di Trieste (VO-AIDA)'; and 'Deliverables' with a 'How to add your application' section. A sidebar on the left contains 'Management', 'Technology', and 'Science' categories. The footer includes a status bar with server information.

<http://dame.na.infn.it/>
Web application PROTOTYPE

The screenshot displays the DAME web application interface. At the top, there is a navigation bar with 'DAta Mining & Exploration' and 'DAME' logos. The main content area is titled 'My Experiments' and features a table of experiments. The table has columns for 'Name', 'Science case', and 'Mode'. Below the table, there is a 'My Filestore' section with a 'Stiglia' button and a link to 'Click here to upload the file'. The interface also shows a user profile for 'Giuseppe longo' with a 'Last Login' of 'Tue 04 Aug 2009 10:33PM GMT'. A sidebar on the left contains navigation links like 'Home', 'Science and Tech', 'MyFilestore', 'MyExperiments', 'Logout', 'Help & Tutorials', and 'The Team'. The bottom of the page shows a 'Completo' status bar with system information.

Name	Science case	Mode
pposo	pposo	pposun
ppovapisto	pposo	pposun
ppovax2	pposo	pposun
pposimo	pposo	pposun
pposax	pposo	pposun
pposax2	pposun	pposun
pposax3	pposun	pposun
pposax4	pposun	pposun
pposax5	pposun	pposun
pposax6	pposun	pposun
pposax7	pposun	pposun
pposax8	pposun	pposun
pposax9	pposun	pposun
pposax10	pposun	pposun
pposax11	pposun	pposun
pposax12	pposun	pposun
pposax13	pposun	pposun
pposax14	pposun	pposun
pposax15	pposun	pposun
pposax16	pposun	pposun
pposax17	pposun	pposun
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pposax46	pposun	pposun
pposax47	pposun	pposun
pposax48	pposun	pposun
pposax49	pposun	pposun
pposax50	pposun	pposun


DAME front-end



Browser tabs: G., F..., P., B..., N., h..., C., W., V..., S W., S..., V..., I..., I..., W., D., M.

Address bar: http://dame.scope.unina.it:8080/FrontEnd/

DAME Application



Workspace Manager

New Workspace

Workspace [Upload] [Experiment] [Rename] [Delete]

No items to show.

Files Manager

Download	File	Last Access	Delete
No items to show.			

Experiment Manager

Experiment	Status	Last Access	Delete
No items to show.			

Help SECTION

DAME plugin wizard



The screenshot shows the 'DMPugin Application Wizard' window. It has a menu bar with 'File' and 'Help'. The main area is divided into several sections:

- Plugin Informations:** Fields for Name (Example), Documentation (http://www.someurl.edu/url), Version (1.0), and Domains (clustering).
- Owner Informations:** Fields for Owner Name (John Smith) and Owner Mail (john@someurl.edu).
- Running Modes Informations:** A table with columns for mode, a checkbox, and documentation/running time fields.
- Components:** A tree view showing a 'Train' folder containing 'Fields' (with 'someField'), 'Input Files' (with 'inputFile'), and 'Output Files' (with 'output').

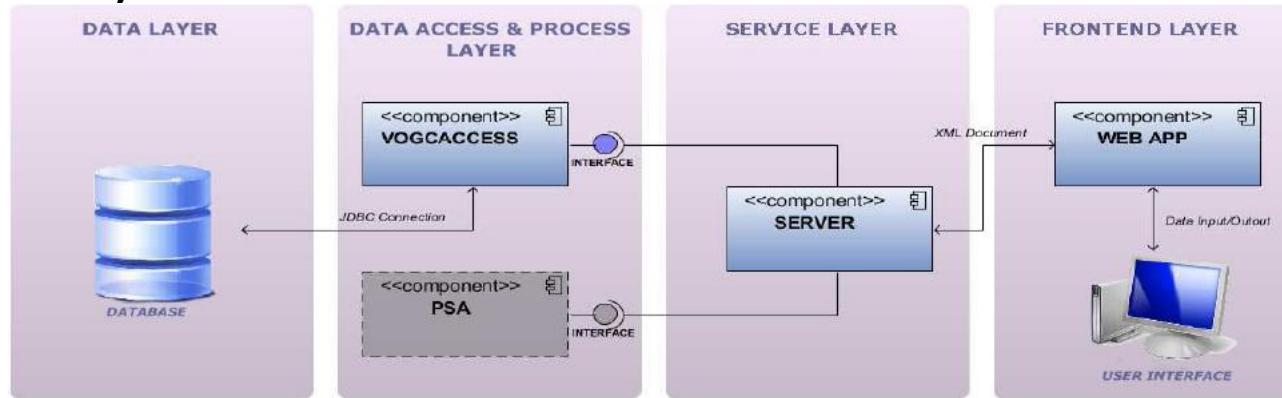
An 'Edit' dialog box is open over the 'output' component, with fields for Name (output), Description (Output File), Format (votable), and a checked 'is Partial' checkbox. A 'Save' button is at the bottom of the dialog. At the bottom of the main window, there are 'Add', 'Delete', and 'Edit' buttons.

Mode	Checkbox	Documentation	Running Time
Train	<input checked="" type="checkbox"/>	http://www.someurl.edu/#train	0
Test	<input type="checkbox"/>		0
Run	<input type="checkbox"/>		0
Full	<input type="checkbox"/>		0

Other DAME based WEB applications



VO-GClusters – Web application for globular clusters (in coll. with M. Castellano, INAF-OAR)



VOGClusters is a sub-framework within DAME for the exploration and mining of VObs data archives for anything related to Globular clusters

Functionalities

- Cross-correlation of complex and bibliographic data
- Interoperability of distributed archives

Part III

DAME APPLICATIONS TO ASTRONOMY



Supervised methods

They learn how to partition the parameter space by means of a training phase based on examples.

Neural Networks such as the Multi Layer Perceptron (MLP), Support Vector Machines (SVM), etc.

Pro's & Con's

- They are good for interpolation of data, **very bad for extrapolations**
- They **need extensive bases of knowledge** (i.e. uniformly sampling the parameter space) which are difficult to obtain;
- Errors are easy to evaluate
- Relatively easy to use

- **They reproduce all biases and preconceived ideas present in the BoK**

Unsupervised (clustering) methods

They cluster the data relying on their statistical properties only
Understanding takes place through labeling (very limited BoK).

Generative Topographic Mapping (GTM), Self Organizing Maps (SOM), Probabilistic Principal Surfaces (PPS), Support Vector Machines (SVM), etc.

Pro's & Con's

- In theory they need little or none knowledge a-priori
- Do not reproduce biases present in the BoK
- Evaluation of errors more complex (through complex statistics)
- They are computationally intensive
- They are not user friendly (... more an art than a science; i.e. lot of experience required)

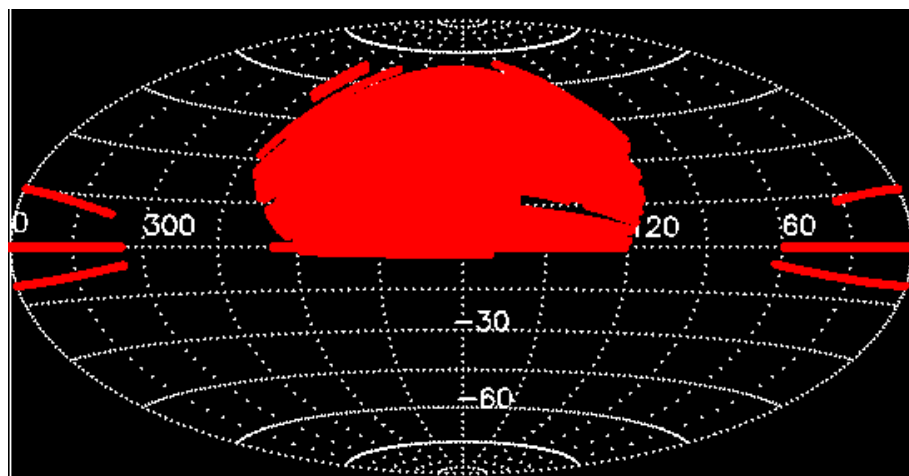
MINING THE SDSS ARCHIVE. I. PHOTOMETRIC REDSHIFTS IN THE NEARBY UNIVERSE

RAFFAELE D’ABRUSCO,^{1,2} ANTONINO STAIANO,³ GIUSEPPE LONGO,^{1,4,5} MASSIMO BRESCIA,^{5,4} MAURIZIO PAOLILLO,^{1,4}
ELISABETTA DE FILIPPIS,^{5,1} AND ROBERTO TAGLIAFERRI^{6,4}*Received 2006 October 11; accepted 2007 March 2*

ABSTRACT

We present a supervised neural network approach to the determination of photometric redshifts. The method was fine-tuned to match the characteristics of the Sloan Digital Sky Survey, and as base of “a priori” knowledge, it exploits the rich wealth of spectroscopic redshifts provided by this survey. In order to train, validate, and test the networks, we used two galaxy samples drawn from the SDSS spectroscopic data set, namely, the general galaxy sample (GG) and the luminous red galaxy subsample (LRG). The method consists of a two-step approach. In the first step objects are classified as nearby ($z < 0.25$) and distant ($0.25 < z < 0.50$), with an accuracy estimated as 97.52%. In the second step, two different networks are separately trained on objects belonging to the two redshift ranges. Using a standard multilayer perceptron operated in a Bayesian framework, the optimal architectures were found to require one hidden layer of 24 (24) and 24 (25) neurons for the GG (LRG) sample. The final results on the GG data set give a robust $\sigma_z \simeq 0.0208$ over the redshift range $[0.01, 0.48]$ and $\sigma_z \simeq 0.0197$ and $\simeq 0.0238$ for the nearby and distant samples, respectively. For the LRG subsample we find instead a robust $\sigma_z \simeq 0.0164$ over the whole range, and $\sigma_z \simeq 0.0160$ and $\simeq 0.0183$ for the nearby and distant samples, respectively. After training, the networks have been applied to all objects in the SDSS table GALAXY matching the same selection criteria adopted to build the base of knowledge, and photometric redshifts for circa 30 million galaxies having $z < 0.5$ were derived. A catalog containing redshifts for the LRG subsample was also produced.

The Sloan Digital Sky Survey (SDSS) data set & BoK

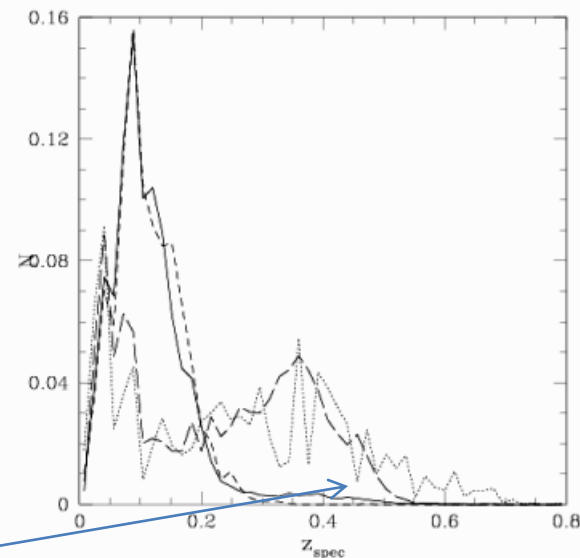
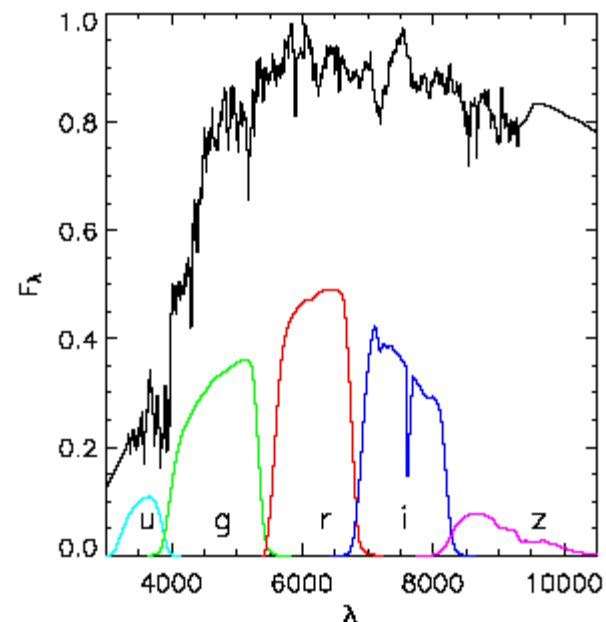


8000 sq degrees
>210 million galaxies
data are public



**Benchmark for almost
everything in observational
cosmology**

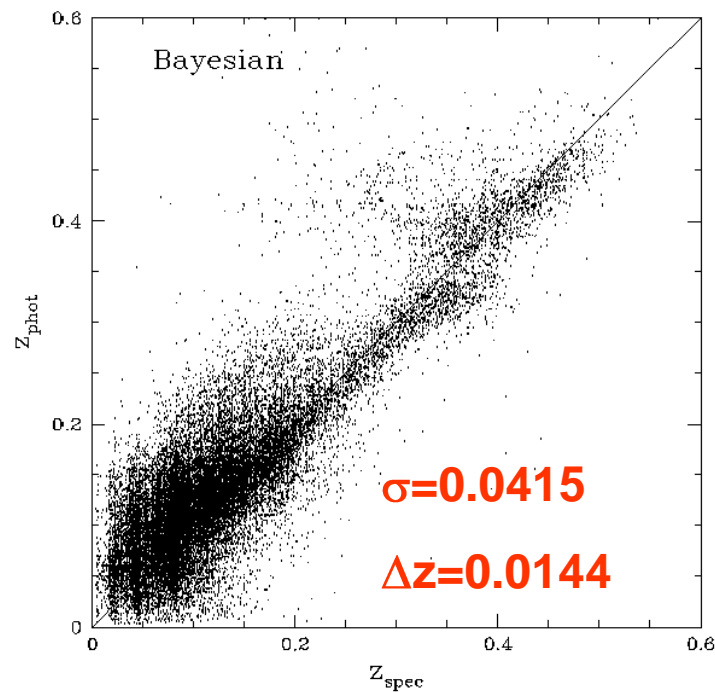
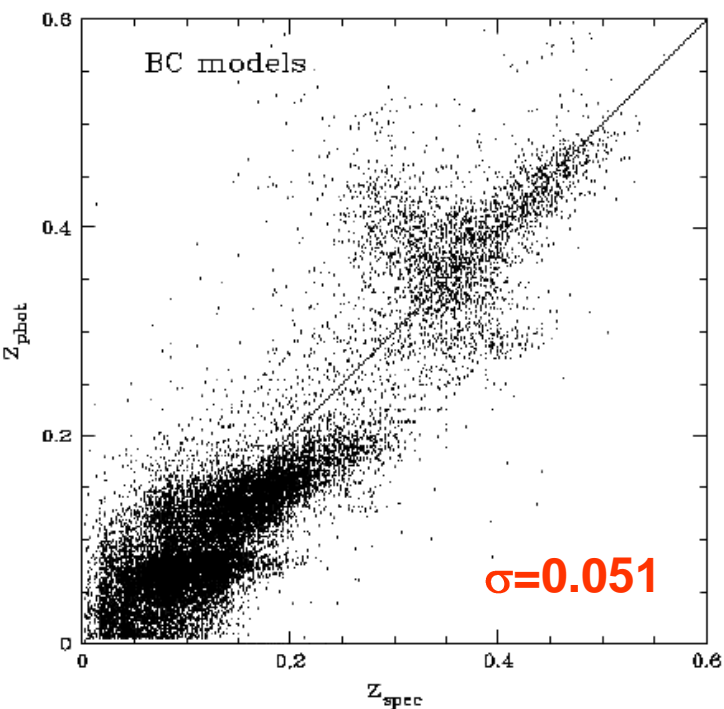
**Extensive but biased
spectroscopic BoK:**
700,000 galaxy spectra



Subsample of about 10^7 Luminous Red Galaxies (LRG)

Fig. 1.— The spectroscopic redshift histogram for the SDSS main EDR (solid), the EDR LRG (long dash), the 2dF (short dash) and the CNOC2 sets.

Some results



type	method	data	Δz_{rms}	Notes	Reference
SEDF	CWW	EDR	0.0666		(Csabai et al. 2003)
	Bruzual-CHARLOT	EDR	0.0552		(Csabai et al. 2003)
	Interpolated	EDR	0.0451		(Csabai et al. 2003)
	Polyomial	EDR	0.0318		(Csabai et al. 2003)
	KD-tree	EDR	0.0254		(Csabai et al. 2003)
	ANNz	EDR	0.0229		(Collister & Lahav 2004)
ML	SVM	EDR	0.027		(Wadadekar 2004)
ML	MLP-feed forward	SDSS-DR1 SDSS-RLG	xx.xxx	yes	(Vanzella et al. 2003)

hybrid interpolation+nearest neighbor

- the color space is partitioned (KD-tree - a binary search tree) into cells containing the same number of objects from the training set
- In each cell fit a second order polynomial.

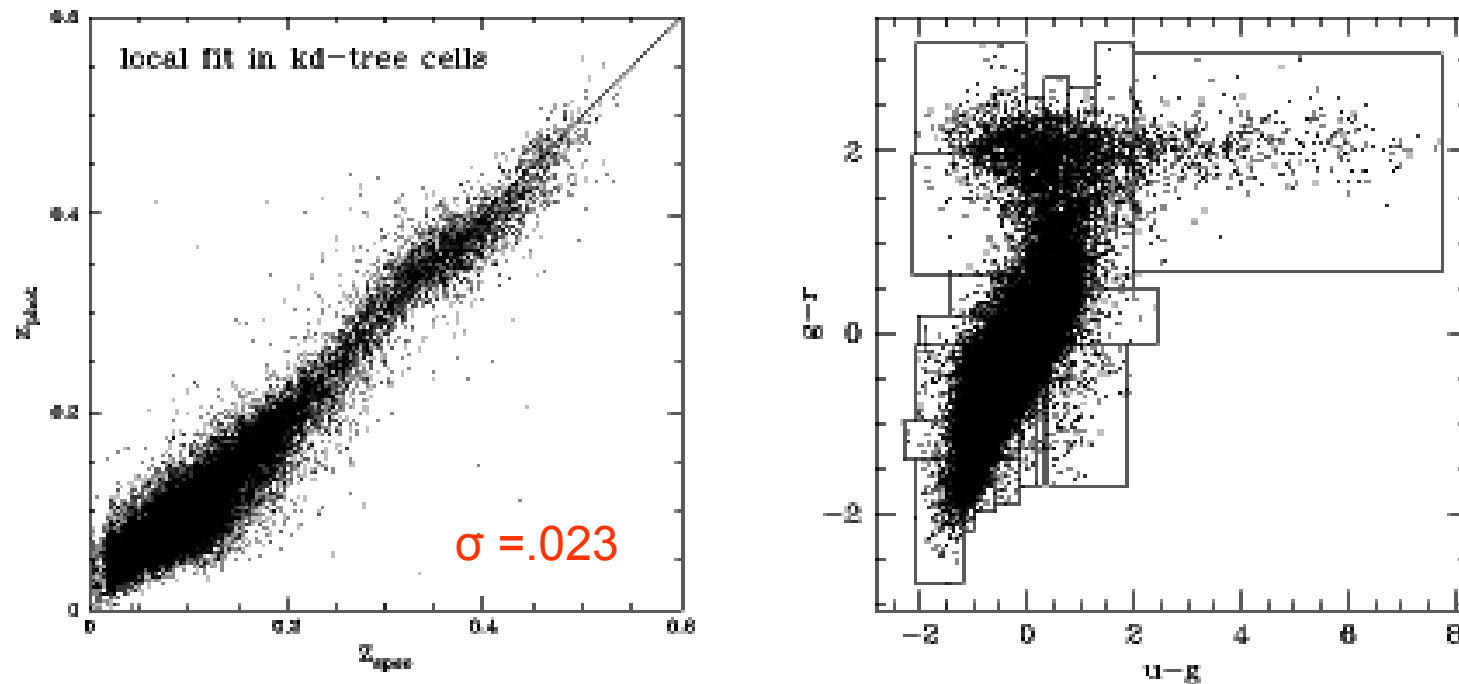
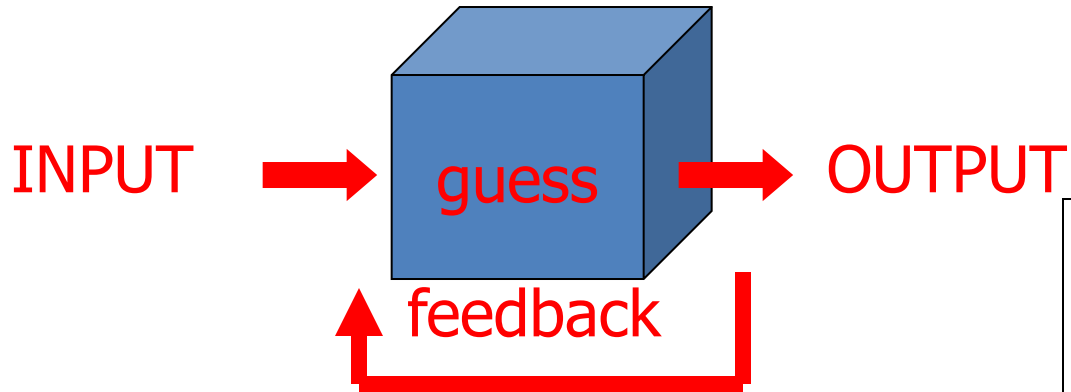
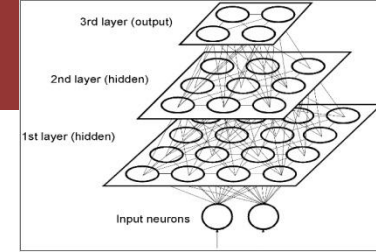


Fig. 4.— On the right we plot a 2 dimensional demonstration of the color space partitioning. In each of these cells we applied the polynomial fitting technique to estimate redshifts. The left figure show the results.

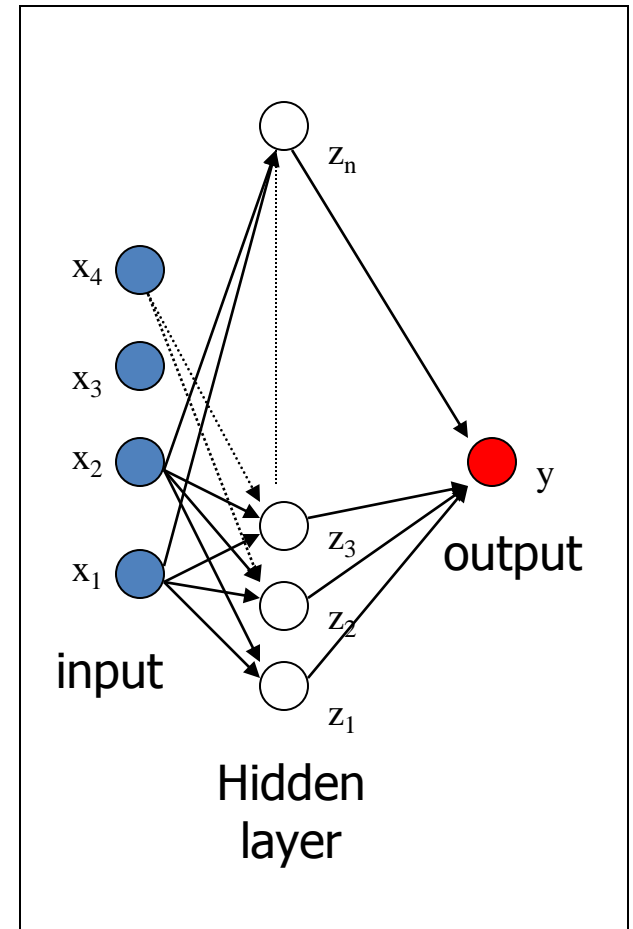
Multi Layer Perceptron



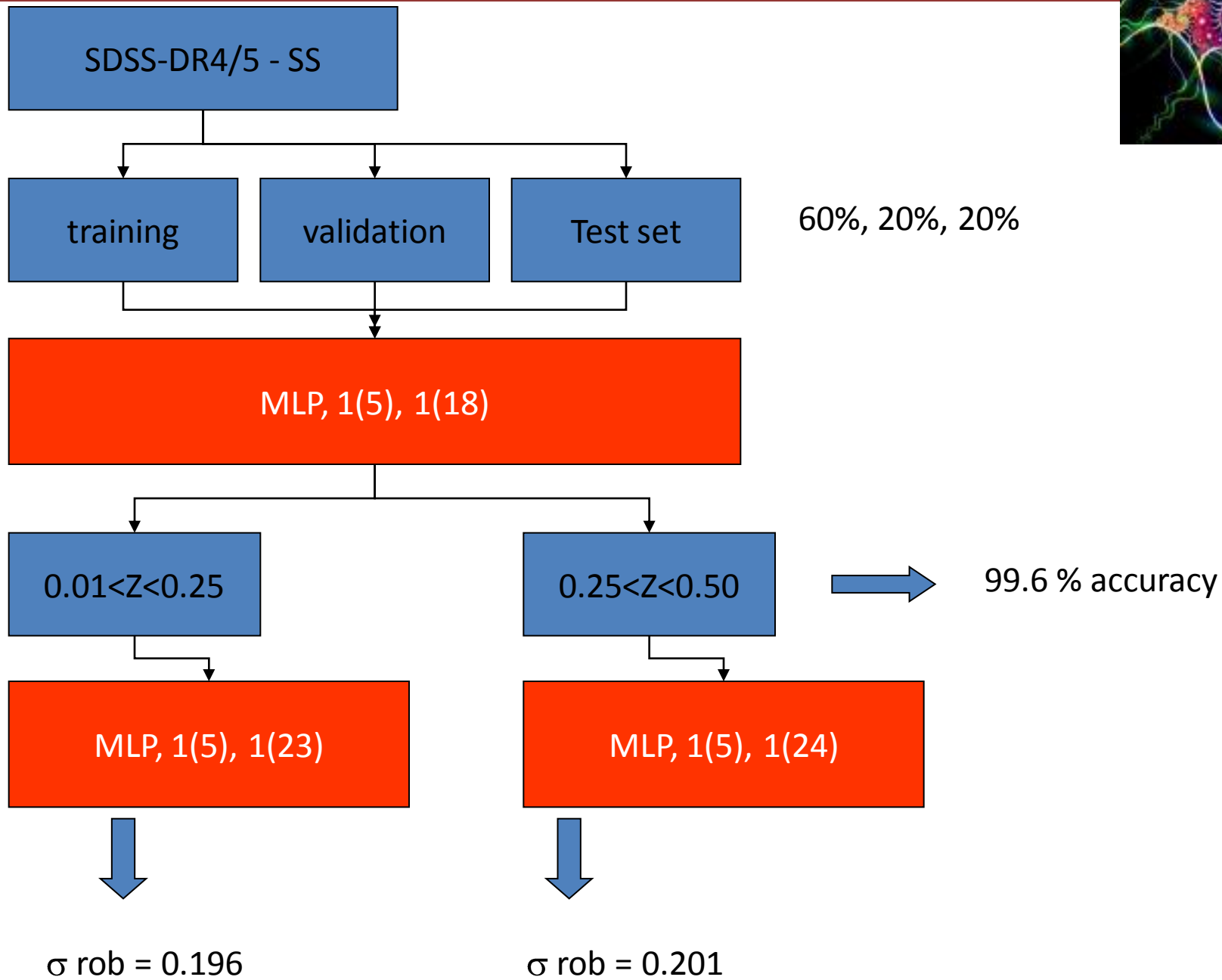
- input layer (n neurons)
- M hidden layer (1 or 2)
- Output layer ($n' < n$ neurons)

Neurons are connected via activation functions

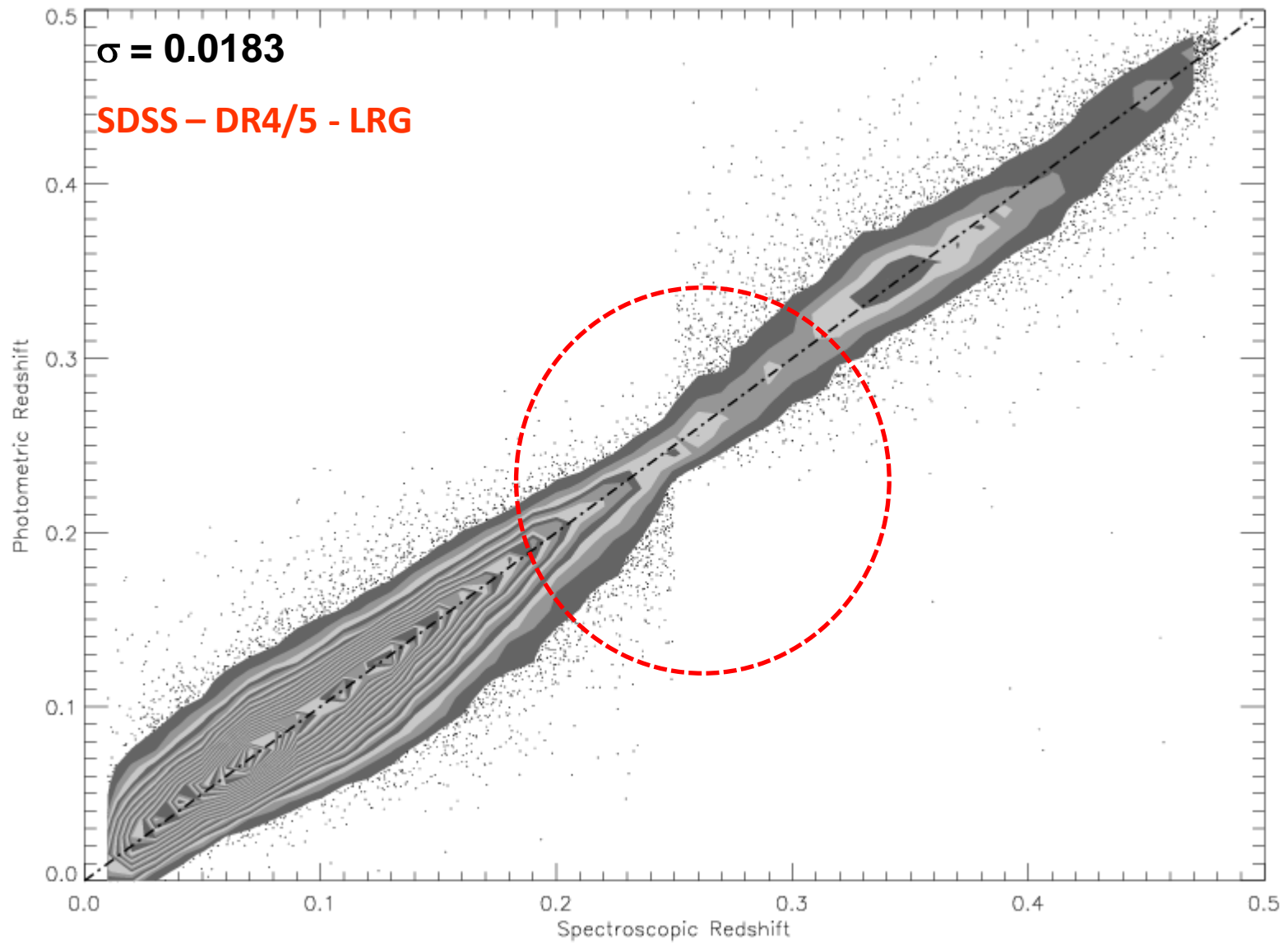
Different NN's given by different topologies,
different activation functions, etc.



VO-Neural approach

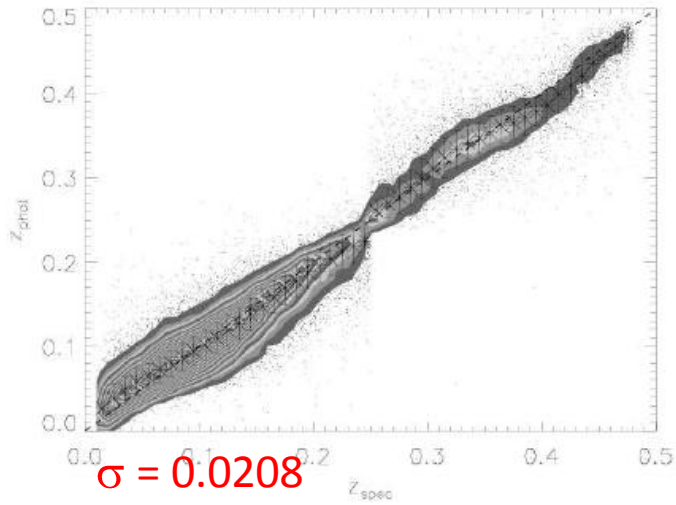


VO-Neural results



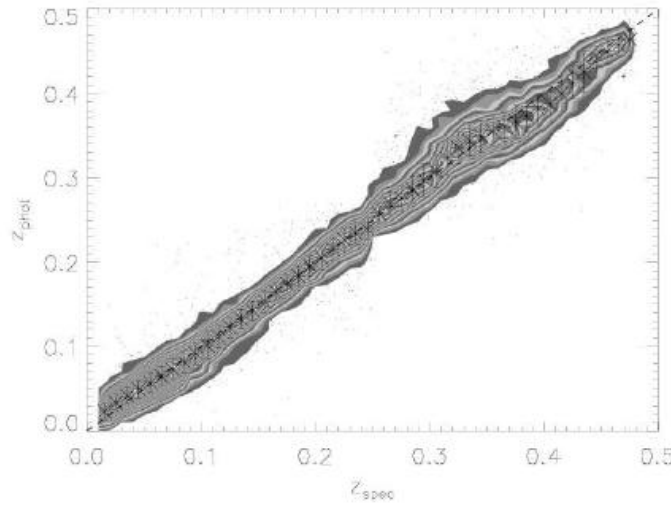
Uneven coverage of parameter space:

General galaxy sample

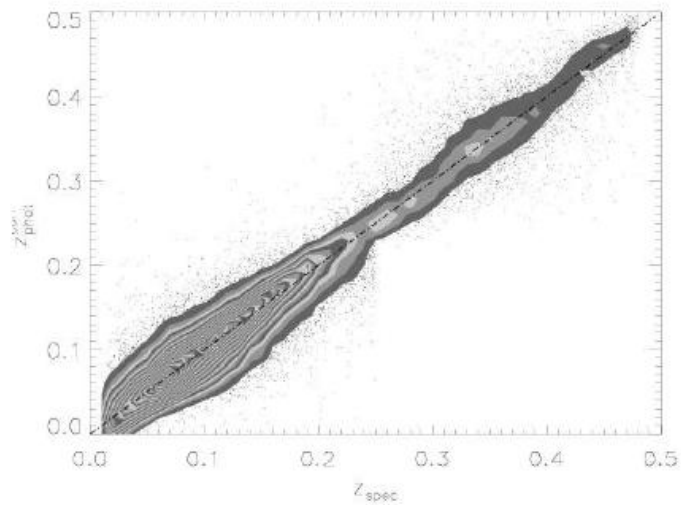


$\sigma = 0.0208$
 $\Delta z = -0.0029$

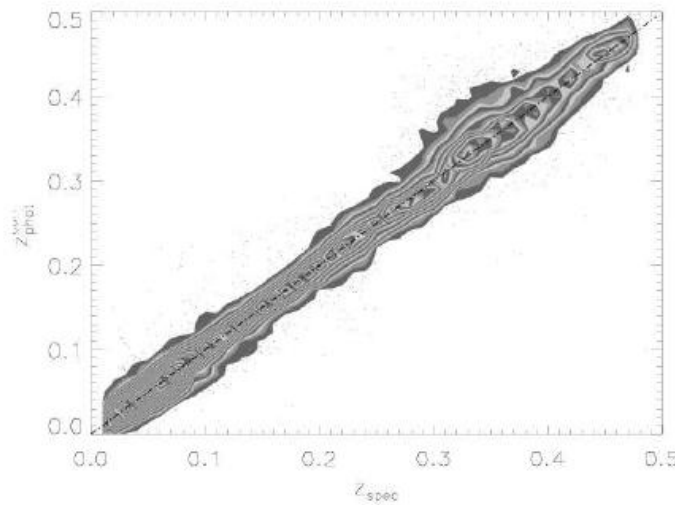
LRG sample



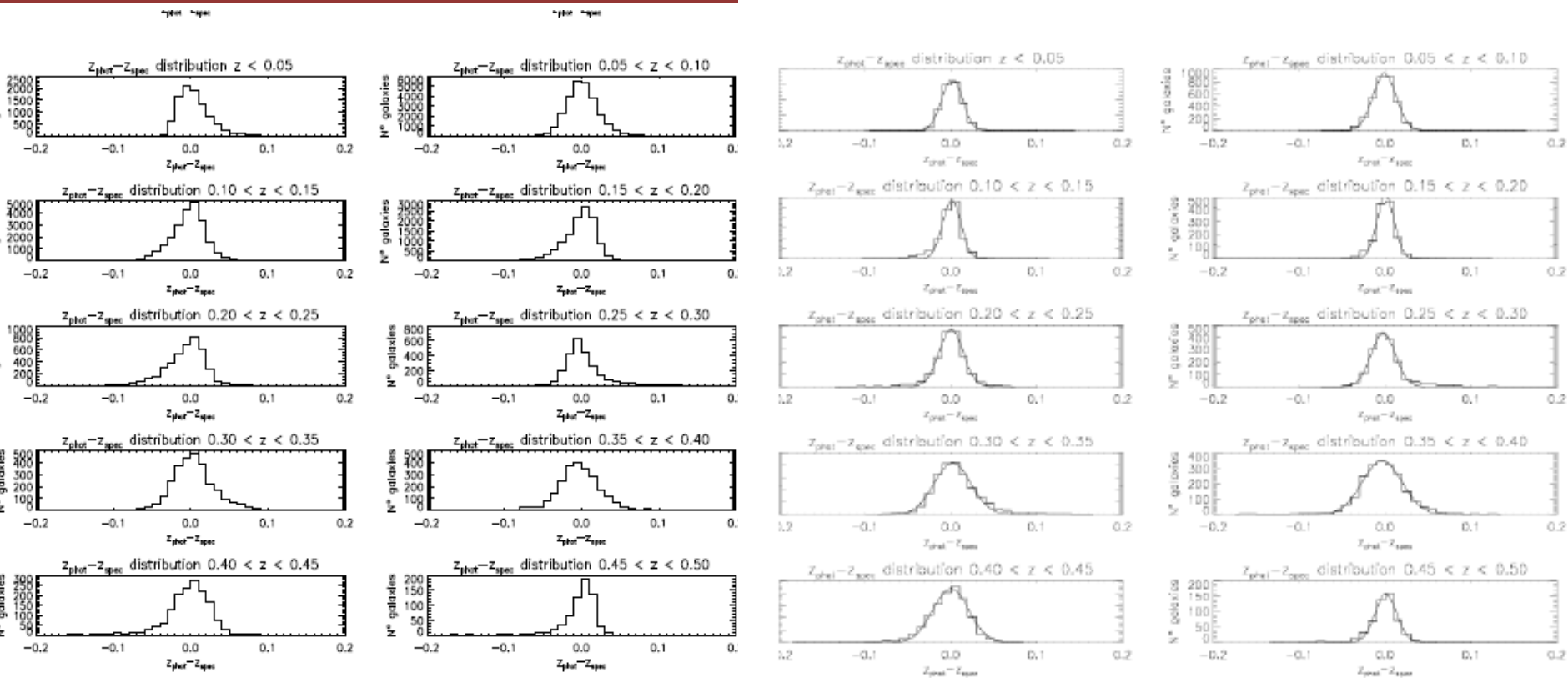
$\sigma = 0.0178$
 $\Delta z = -0.0011$



Non LRG only
 $\sigma = 0.0363$
 $\Delta z = -0.0030$



Errors can be easily evaluated



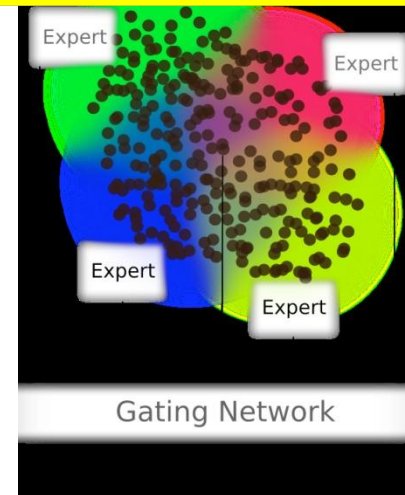
General galaxy sample

LRG sample

And are, on average, well behaved...

What do we learn if the BoK is biased:

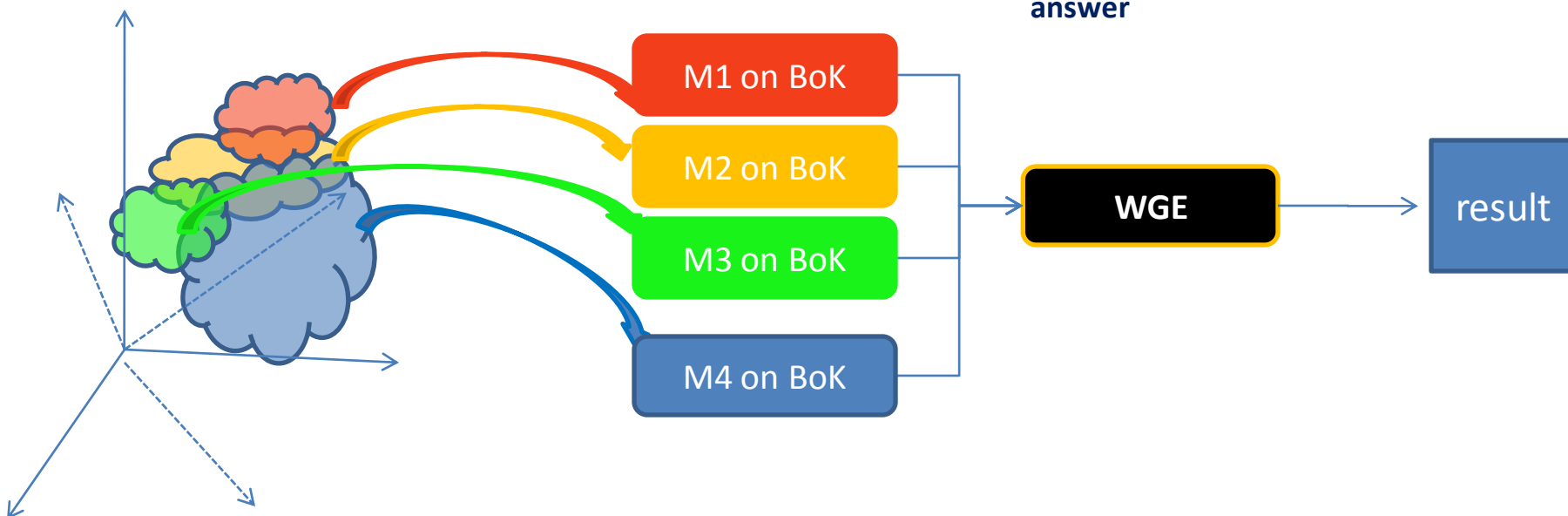
- At high z LRG dominate and interpolative methods are not capable to “generalize” rules
- An unique method optimizes its performances on the parts of the parameter space which are best covered in the BoK



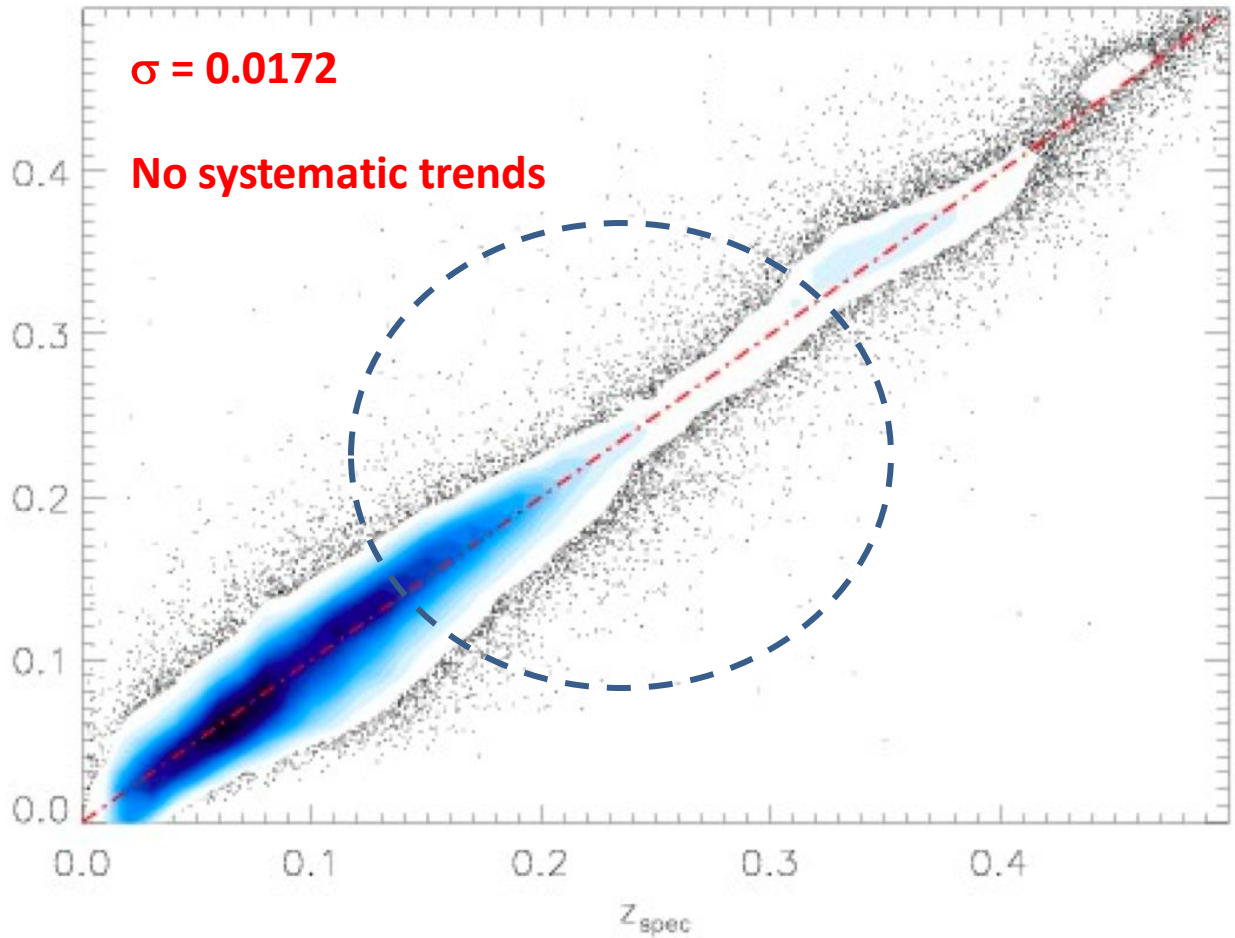
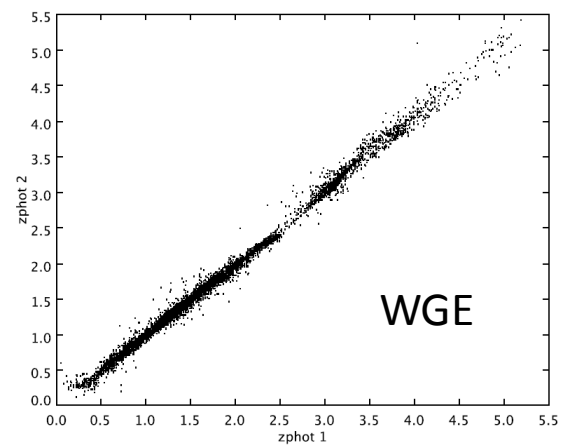
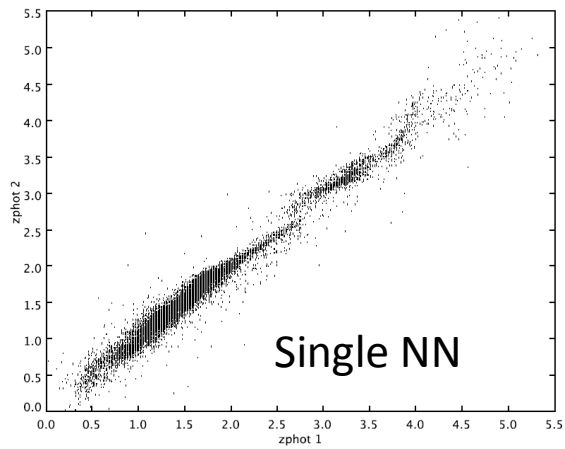
Step 1:
unsupervised clustering in parameter space

Step 2:
supervised training of different NN for each cluster

Step 3:
output of all NN go to WGE which learns the correct answer



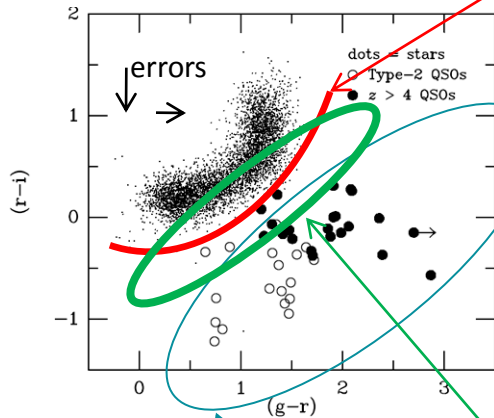
Laurino et al. 2009a,2009b



PART II - applications to observational cosmology

Photometric selection of candidate QSO's (as a clustering problem)

Traditional way to look for candidate QSO in 3 band survey



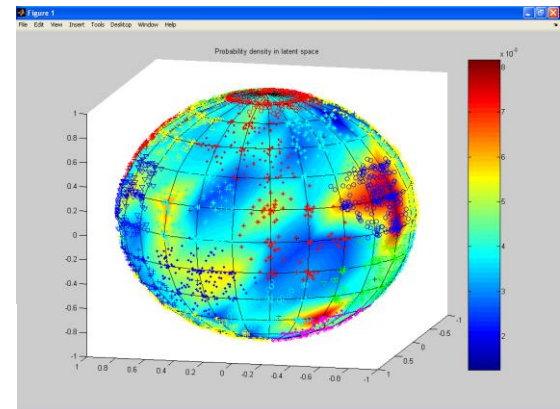
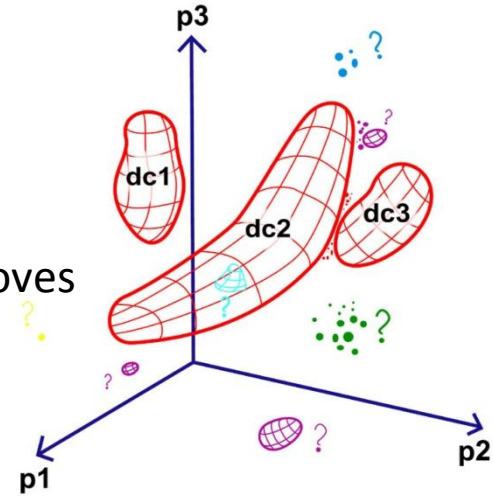
Cutoff line

Candidate QSOs for spectroscopic follow-up's

Ambiguity zone

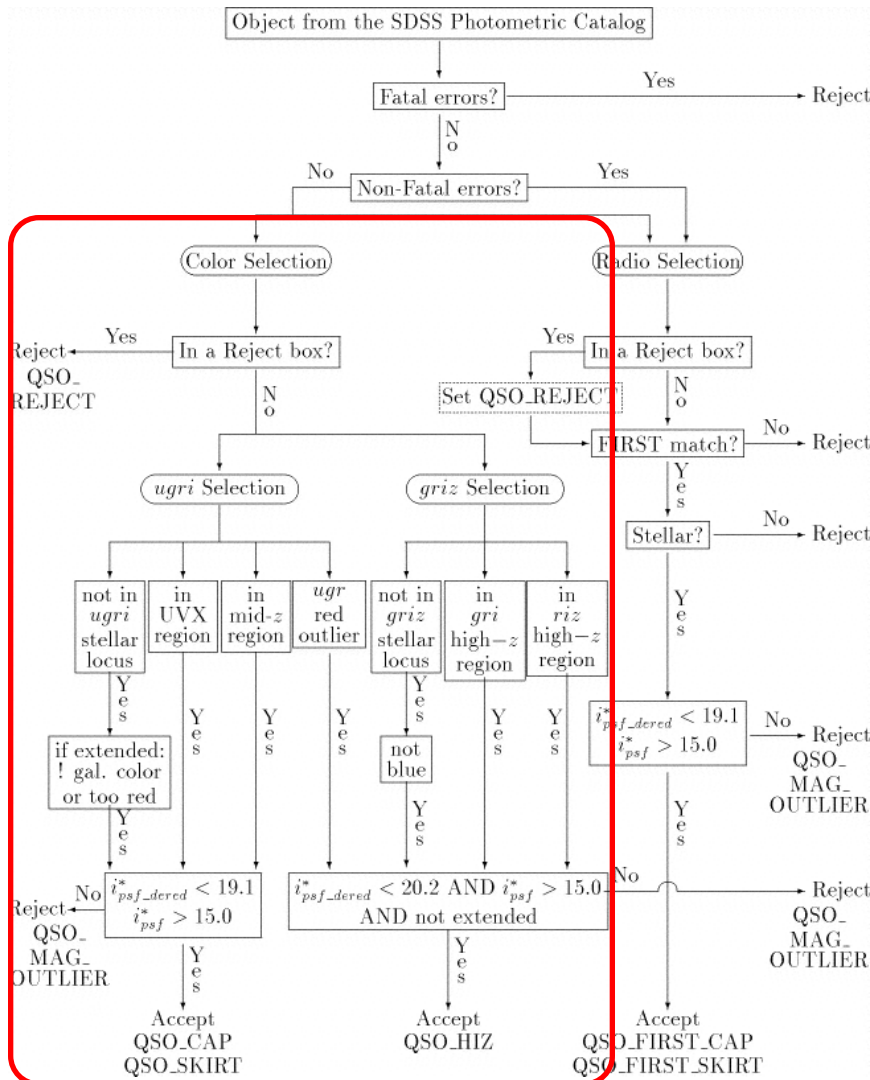
Adding one feature improves separation...

A Generic Machine-Assisted Discovery Problem: Data Mapping and a Search for Outliers



PPS projection of a 21-D parameter space showing as blue dots the candidate quasars. Notice better disentanglement

SDSS QSO candidate selection algorithm (Richards et al, 2002) targets star-like objects as QSO candidate according to their position in the SDSS colours space (u-g,g-r,r-i,i-z), if one of these requirements is satisfied:

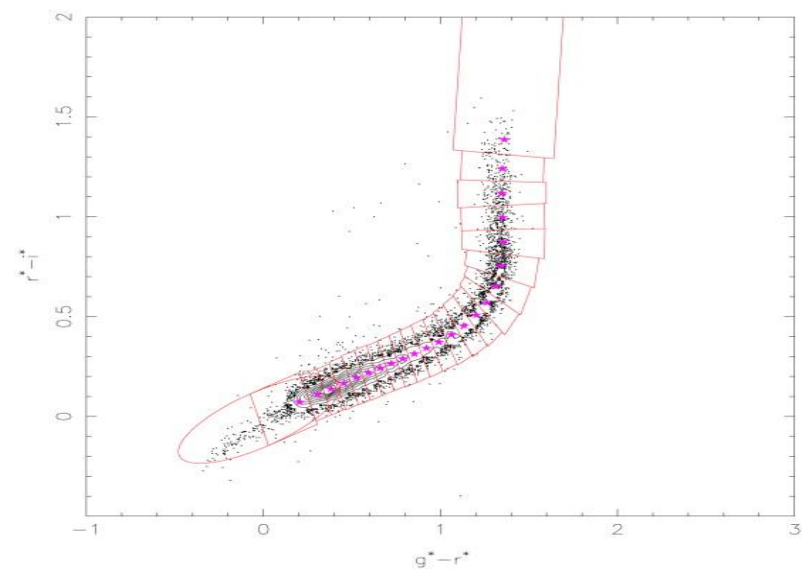
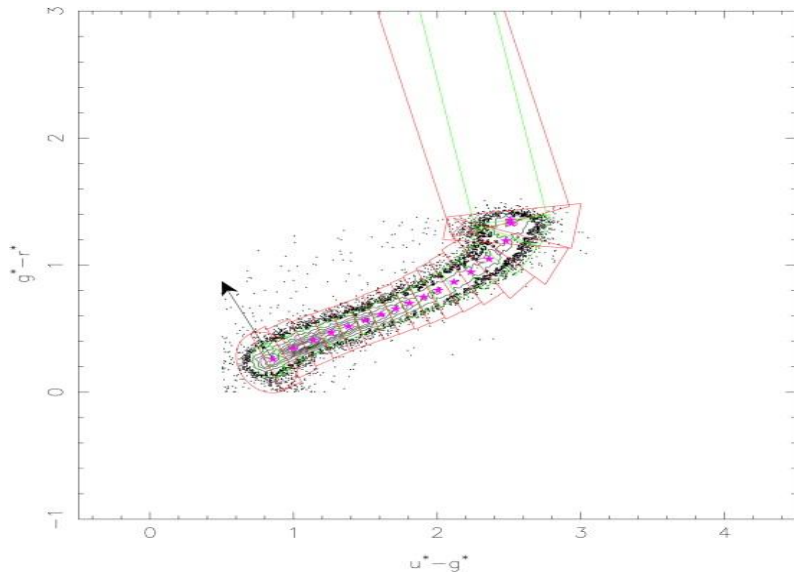


- QSOs are supposed to be placed $>4\sigma$ far from a cylindrical region containing the “stellar locus” (S.L.), where σ depends on photometric errors.

OR

- QSOs are supposed to be placed inside the inclusion regions, even if not meeting the previous requirement.

$c = 95\%$, $e = 65\%$
locally less

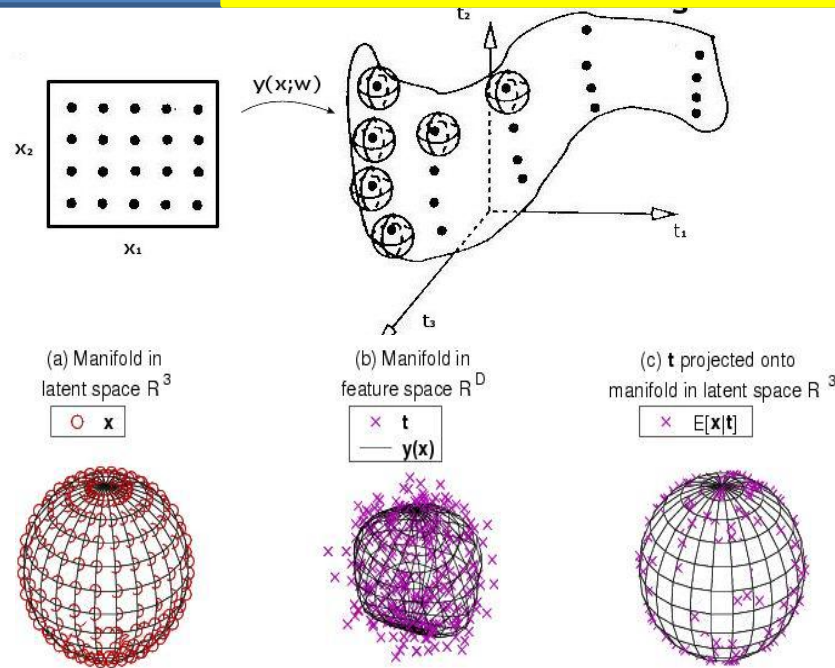


- 1. inclusion regions** are regions where S.L. meets QSO's area (due to absorption from Ly α forest entering the SDSS filters, which changes continuum power spectrum power law spectral index). All objects in these areas are selected so to sample the [2.2, 3.0] redshift range (where QSO density is also declining), but at the cost of a worse efficiency (Richards et al, 2001).
- 2. exclusion regions** are those regions outside the main "stellar locus" clearly populated by stars only (usually WDs). All objects in these regions are discarded.

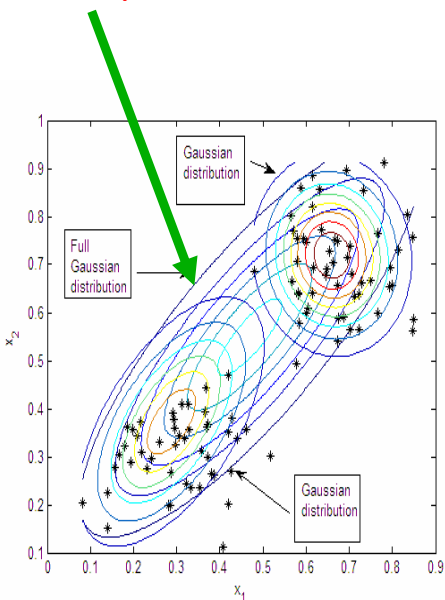
Overall performance of the algorithm: completeness $c = 95\%$, efficiency $e = 65\%$, but locally (in colours and redshift) much less.

Step 1: Unsupervised clustering

PPS determines a large number of distinct groups of objects: nearby clusters in the colours space are mapped onto the surface of a sphere.

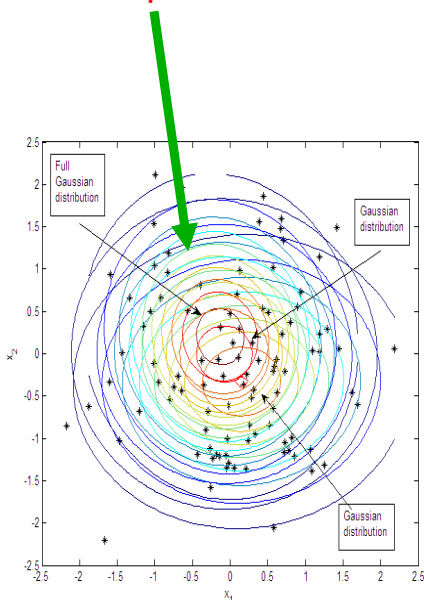


Not replaced!



NegE=750

Replaced!

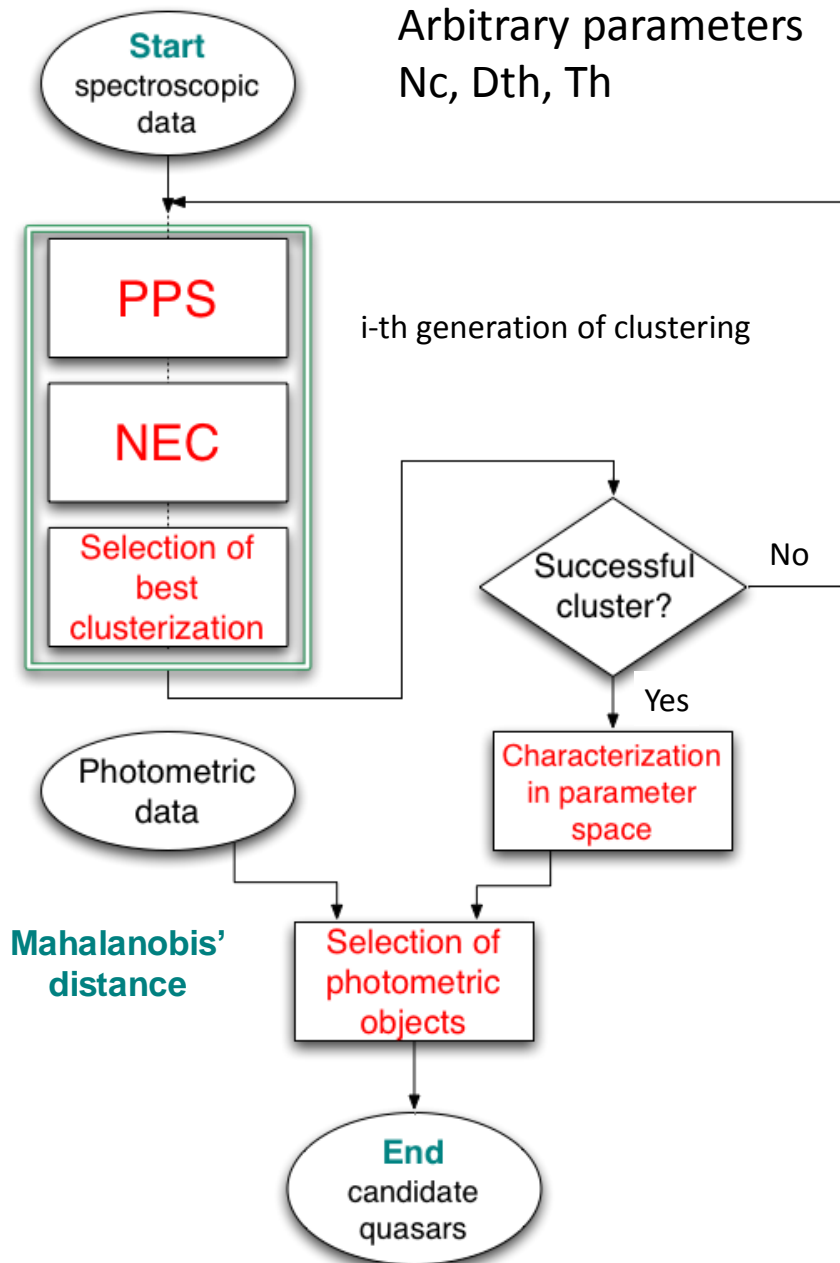


NegE=4

Step 2: Cluster agglomeration

NEC aggregates clusters from PPS to a (a-priori unknown) number of final clusters.

- Plateau analysis:** final number of clusters $N(D)$ is calculated over a large interval of D , and critical value(s) D_{th} are those for which a plateau is visible.
- Dendrogram analysis:** the stability threshold(s) D_{th} can be determined observing the number of branches at different levels of the graph.



To determine the critical dissimilarity D_{th} threshold we rely not only on a stability requirement.

A cluster is successful if fraction of confirmed QSO is higher than assumed fractionary value (Th)

D_{th} is required to maximize **NSR**

$$NSR = \frac{\text{Number of successful clusters}}{\text{Number of total clusters}}$$

The process is recursive: feeding merged unsuccessful clusters in the clustering pipeline until no other successful clusters are found.

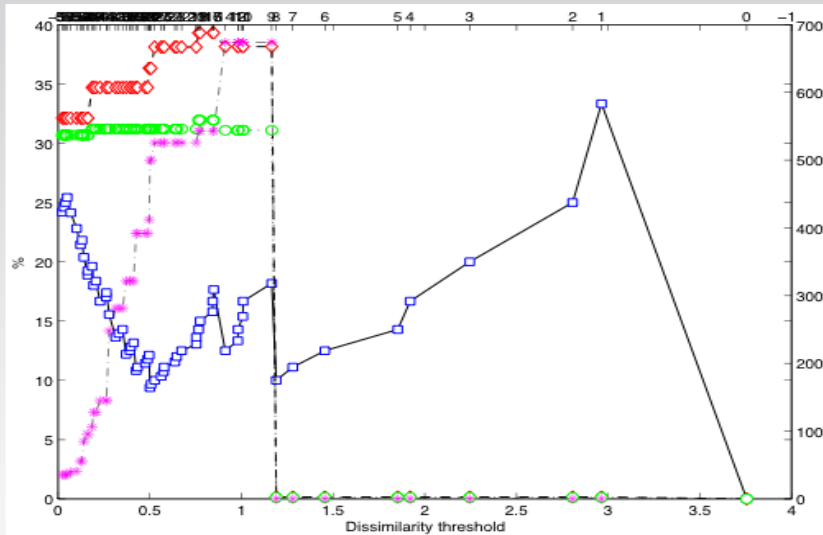
The overall efficiency of the process e_{tot} is the sum of weighed efficiencies e_i for each generation:

$$e_{tot} = \sum_{i=1}^n e_i$$

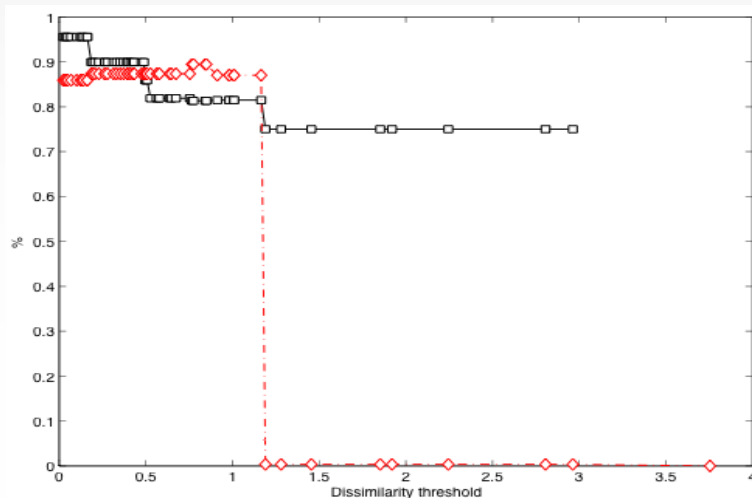
An example of “tuning”

Choice of the clustering

NSR



Efficiency and completeness



e and c estimation

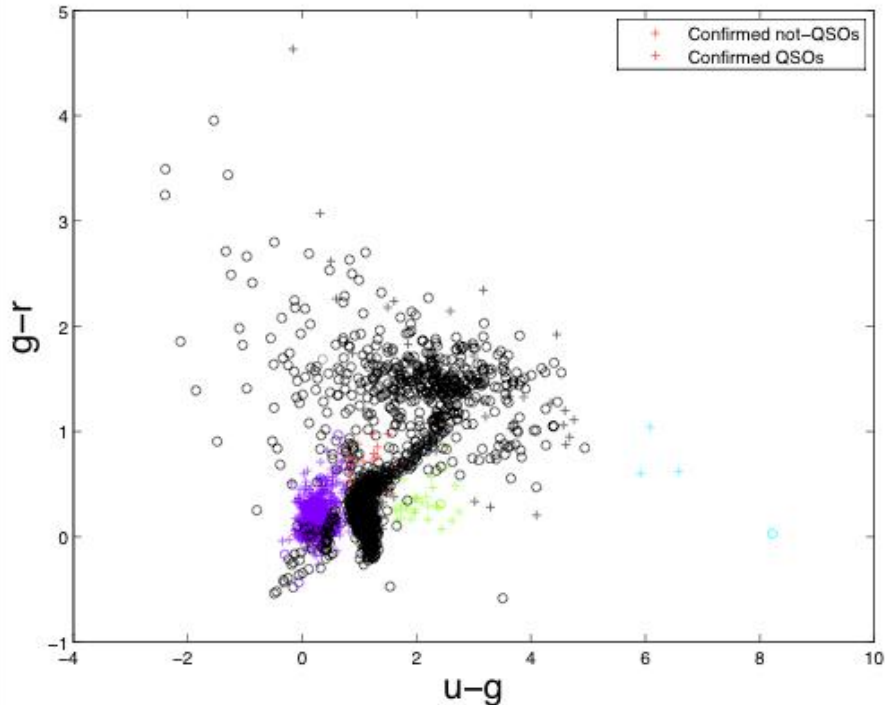
To assess the reliability of the algorithm, the same objects used for the “training” phase have been re-processed using photometric informations only. Results have been compared to the BoK.

algorithm \ labels	QSOs	not QSOs
QSOs	759	72
not QSOs	83	1327

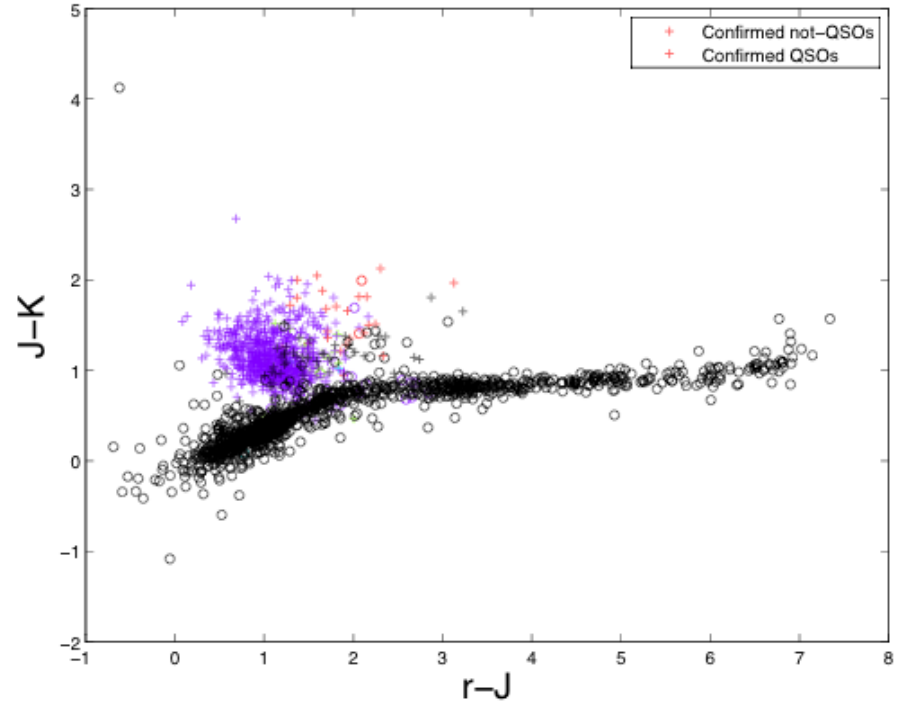
$e = 83.4\%$ $c = 89.6\%$

Confusion matrix

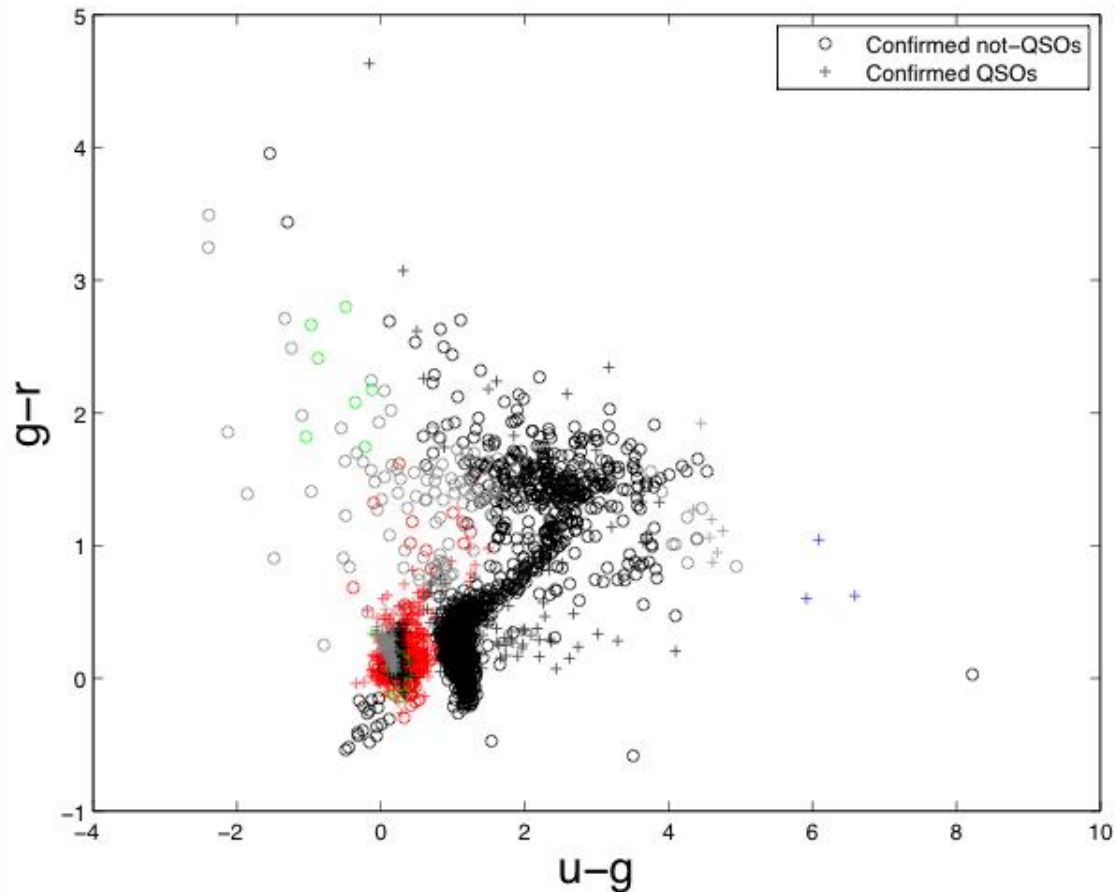
u - g vs g - r



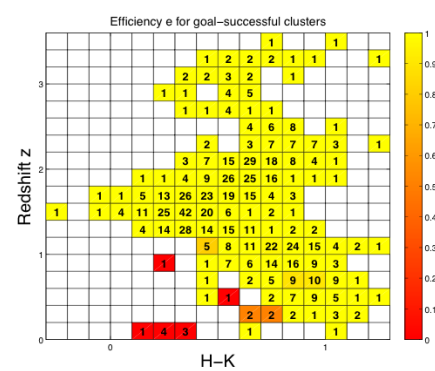
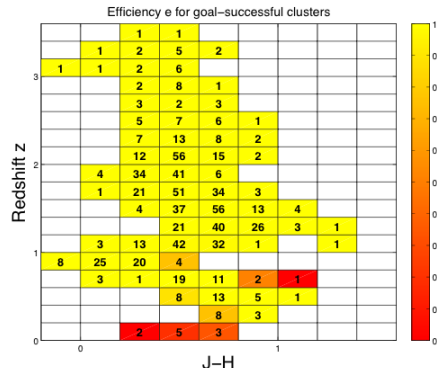
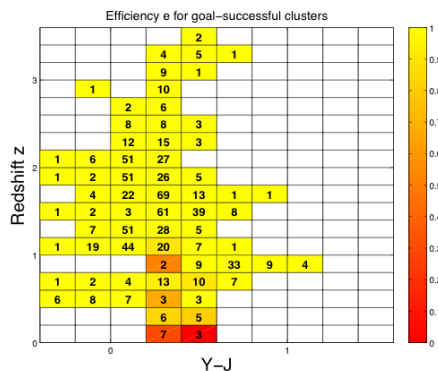
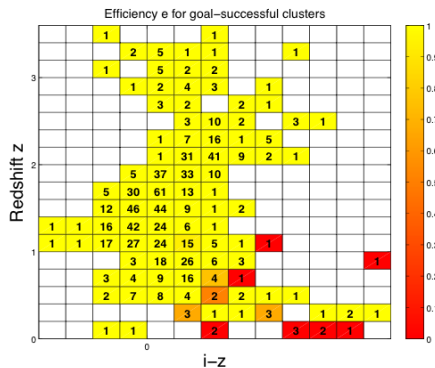
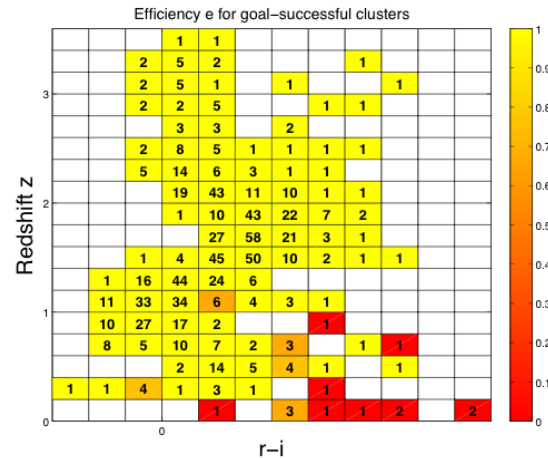
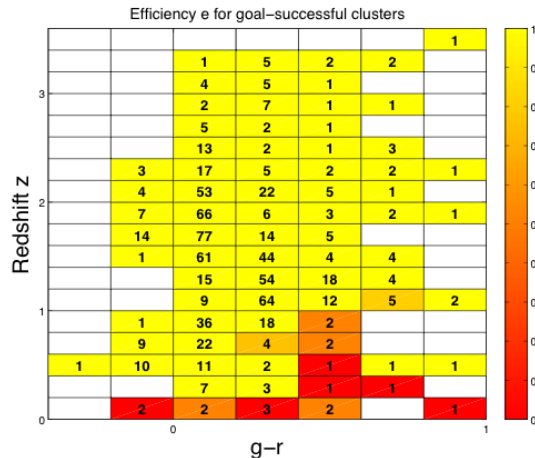
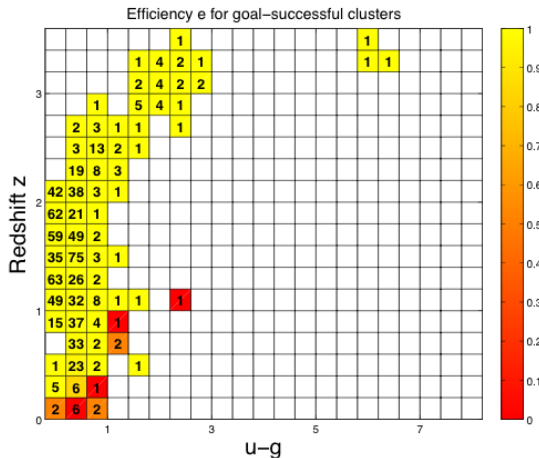
r - J vs J - K



Only a fraction (43%) of these objects have been selected as candidate QSO's by SDSS targeting algorithm in first instance: the remaining sources have been included in the spectroscopic program because they have been selected in other spectroscopic programmes (mainly stars).

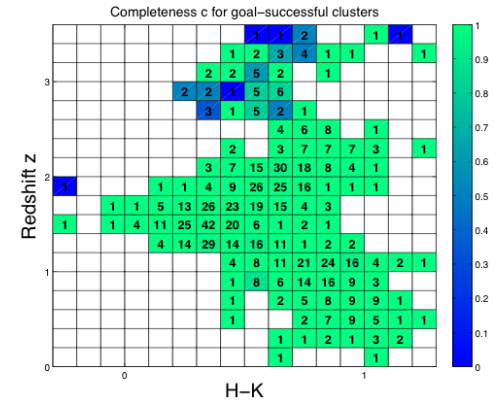
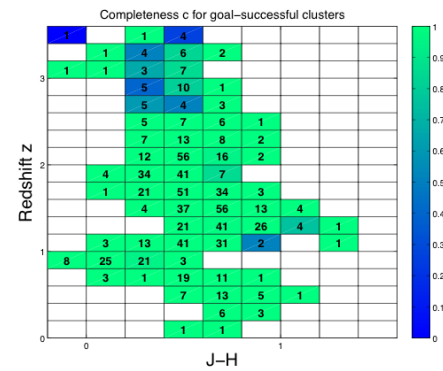
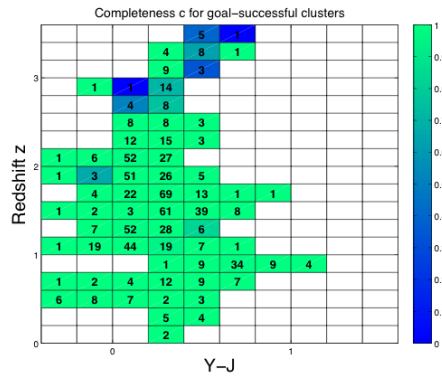
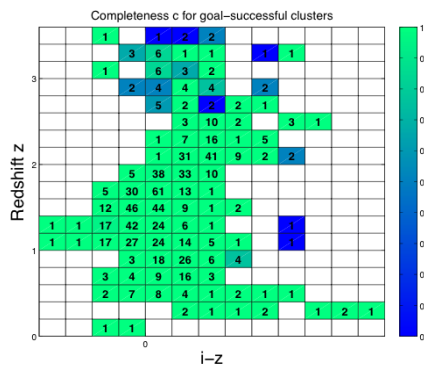
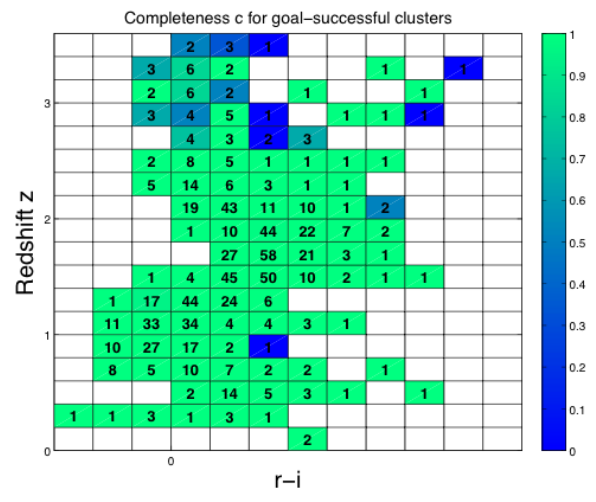
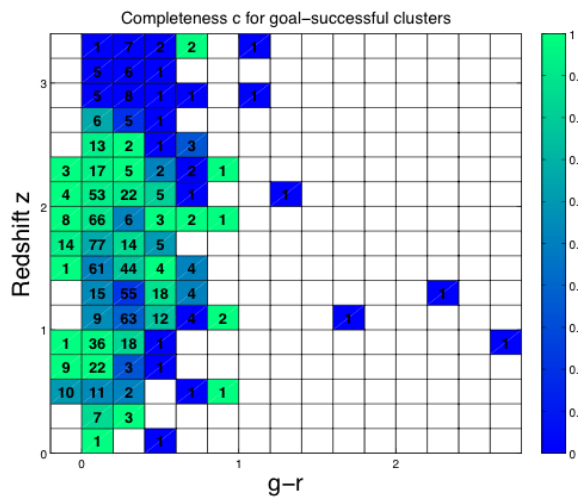
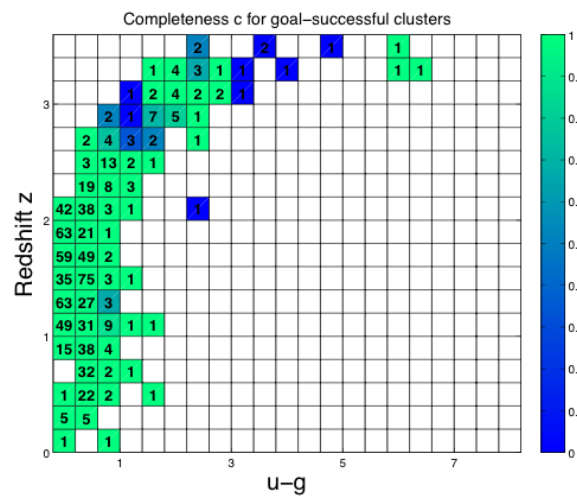
u - g vs g - r

In this experiment the clustering has been performed on the same sample of the previous experiment, using only optical colours.



Experiment 2:
local values of e

Experiment 2: local values of c



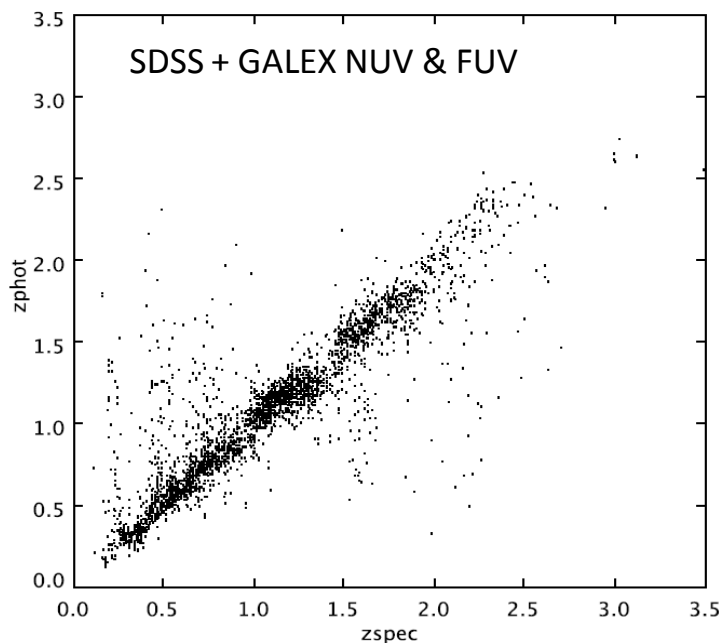
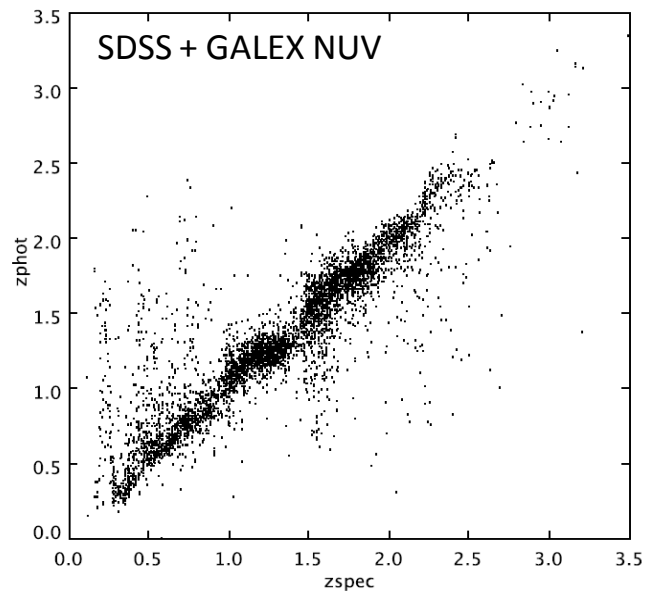
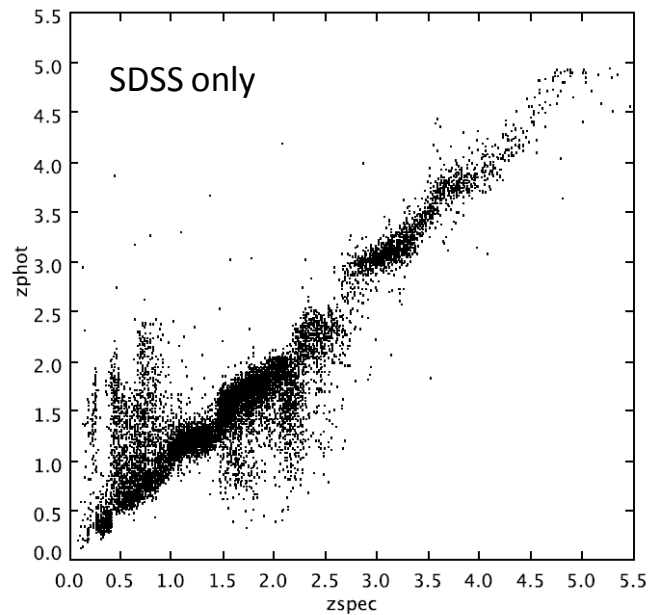


<u>Sample</u>	<u>Parameters</u>	<u>Labels</u>	<u>E_{tot}</u>	<u>C_{tot}</u>	<u>N_{gen}</u>	<u>N_{suc. clus}</u>
Optical QSO candidates (1)	SDSS colours	'specClass'	83.4 % (0.3 %)	89.6 % (0.6 %)	2	(3,0)
Optical + NIR star-like objects (2)	SDSS colours + UKIDSS colours	'specClass'	91.3 % (0.5 %)	90.8 % (0.5 %)	3	(3,1,0)
Optical + NIR star-like objects (3)	SDSS colours	'specClass'	92.6 % (0.4 %)	91.4 % (0.6 %)	3	(3,0,1)

The catalogue of candidate quasars is publicly available at the URL:

http://voneural.na.infn.it/catalogues_qsos.html

BUT ... LET'S GO BACK TO PHOT-Z

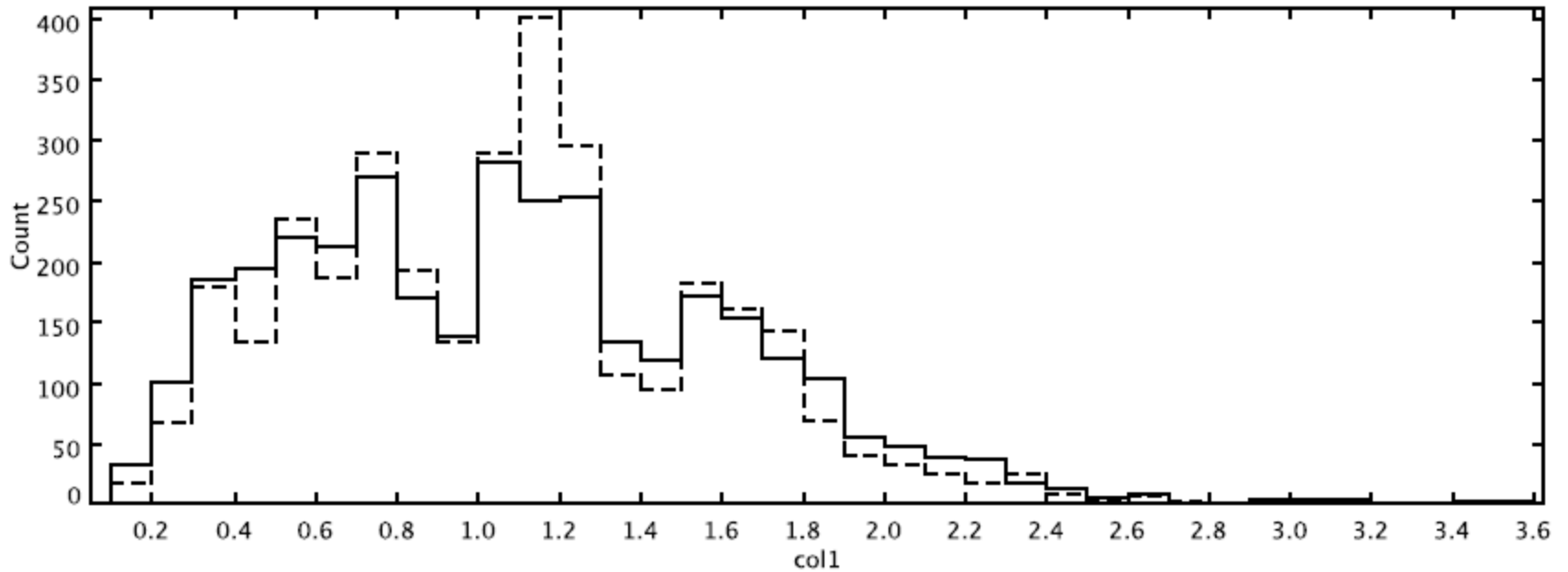


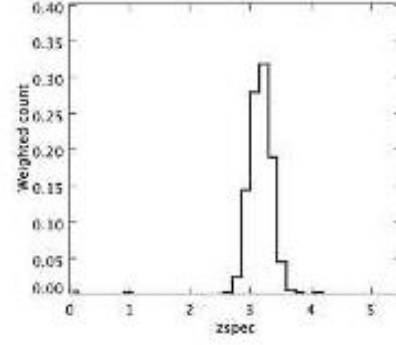
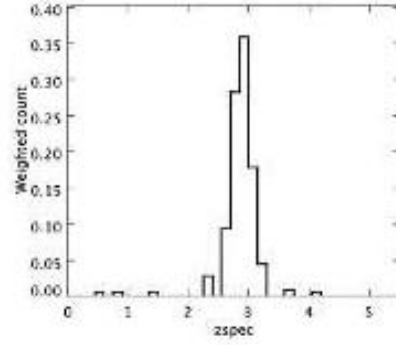
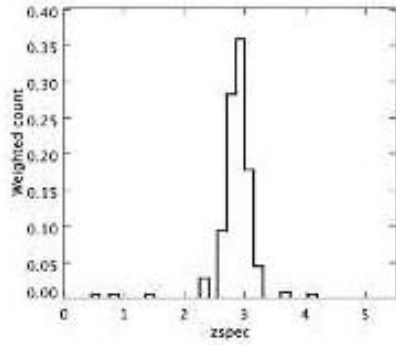
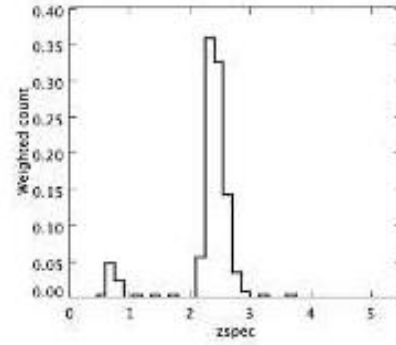
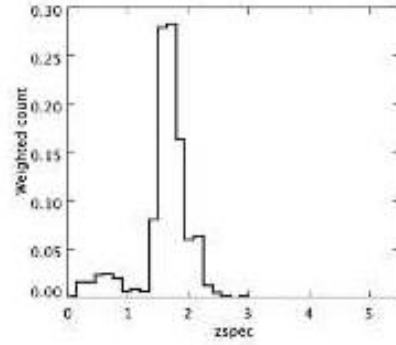
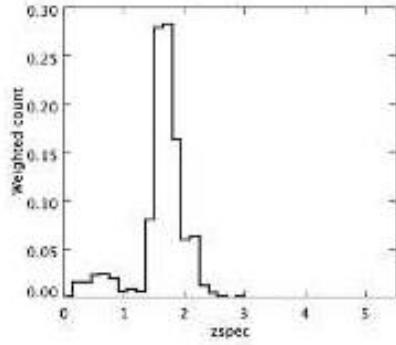
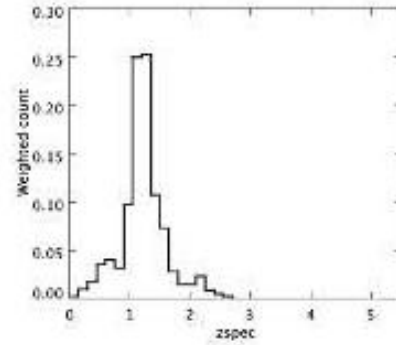
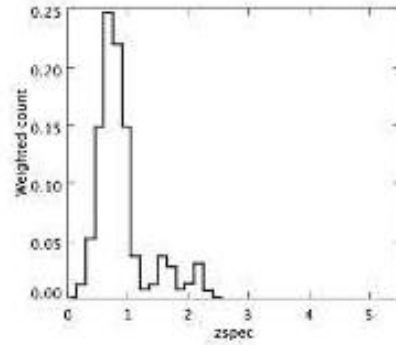
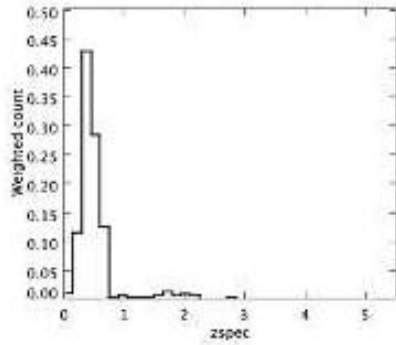
No need for fine tuning !!!

Only New BoK !!!



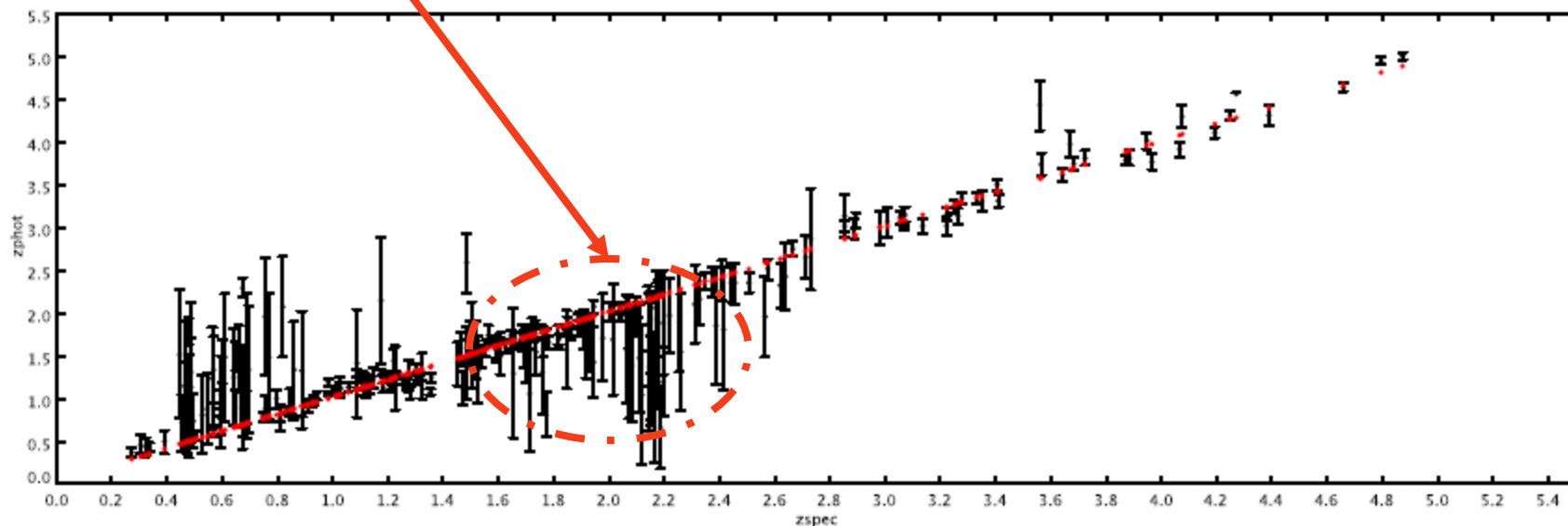
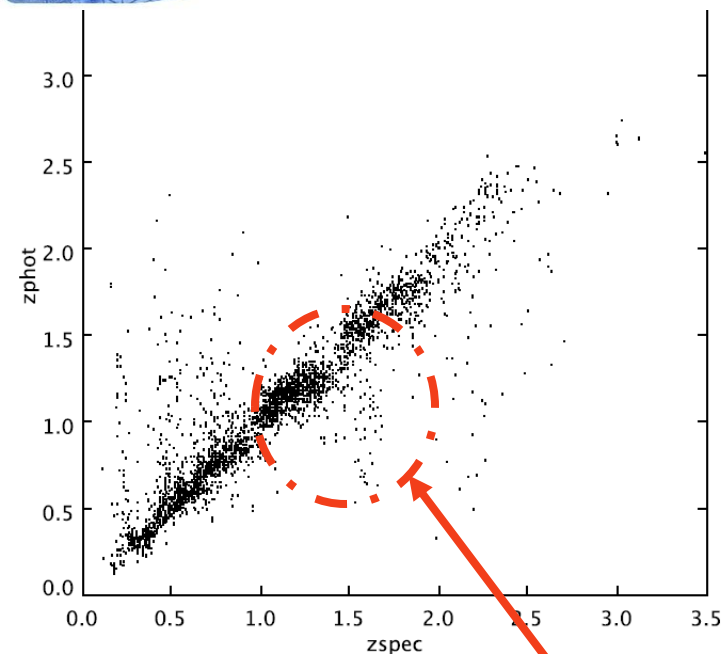
Distribution of Z_spec (solid) and Z_phot (dashed) for test set !!!!





Errors:

- **Input noise:** error propagation on the input parameter (Ball et al. 2008)
- **Model variance:** different models make differing predictions (Collister & Lahav 2004)
- **Model bias:** different models may be affected by different biases.
- **Target noise:** in some regions of the parameter space, data may represent poorly the relation between featured and targets (*Laurino 2009*).



So far restricted choice of problems

Tagliaferri et al. 2003	Ball & Brunner 2009	BoK
S/G separation	S/G separation	Y
Morphological classification of galaxies <i>(shapes, spectra)</i>	Morphological classification of galaxies <i>(shapes, spectra)</i>	Y
Spectral classification of stars	Spectral classification of stars	Y
Image segmentation	-----	
Noise removal <i>(grav. waves, pixel lensing, images)</i>	-----	
Photometric redshifts <i>(galaxies)</i>	Photometric redshifts <i>(galaxies, QSO's)</i>	Y
Search for AGN	Search for AGN and QSO	Y
Variable objects	Time domain	
Partition of photometric parameter space for specific group of objects	Partition of photometric parameter space for specific group of objects	Y
Planetary studies (asteroids)	Planetary studies (asteroids)	Y
Solar activity	Solar activity	Y
Interstellar magnetic fields	----	
Stellar evolution models	----	

Limited number of problems due to limited number of reliable BoKs

Bases of knowledge

(set of well known templates for supervised (training) or unsupervised (labeling) methods)

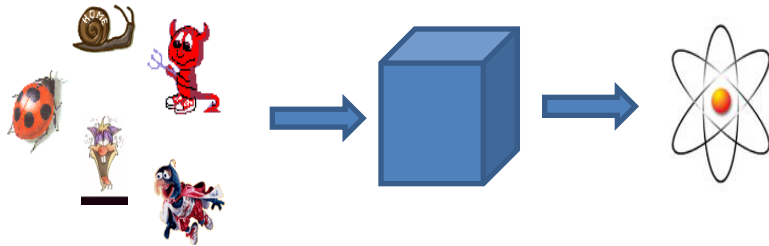
So far

- Limited number of BoK (and of limited scope) available
- Painstaking work for each application (es. spectroscopic redshifts for photometric redshifts training).
- Fine tuning on specific data sets needed (e.g., if you add a band you need to re-train the methods)

Bases of knowledge need to be built automatically from Vobs Data repositories

Community believes AI/DM methods are black boxes

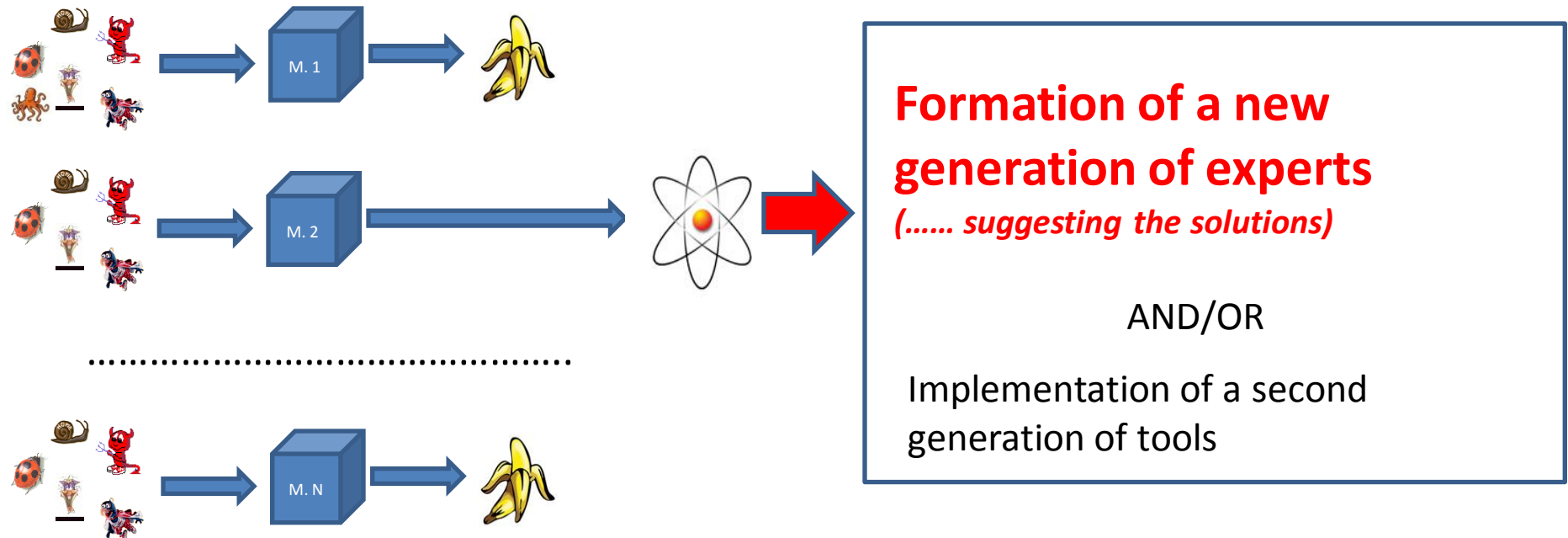
You feed in something, and obtain patters, trends, i.e. knowledge....

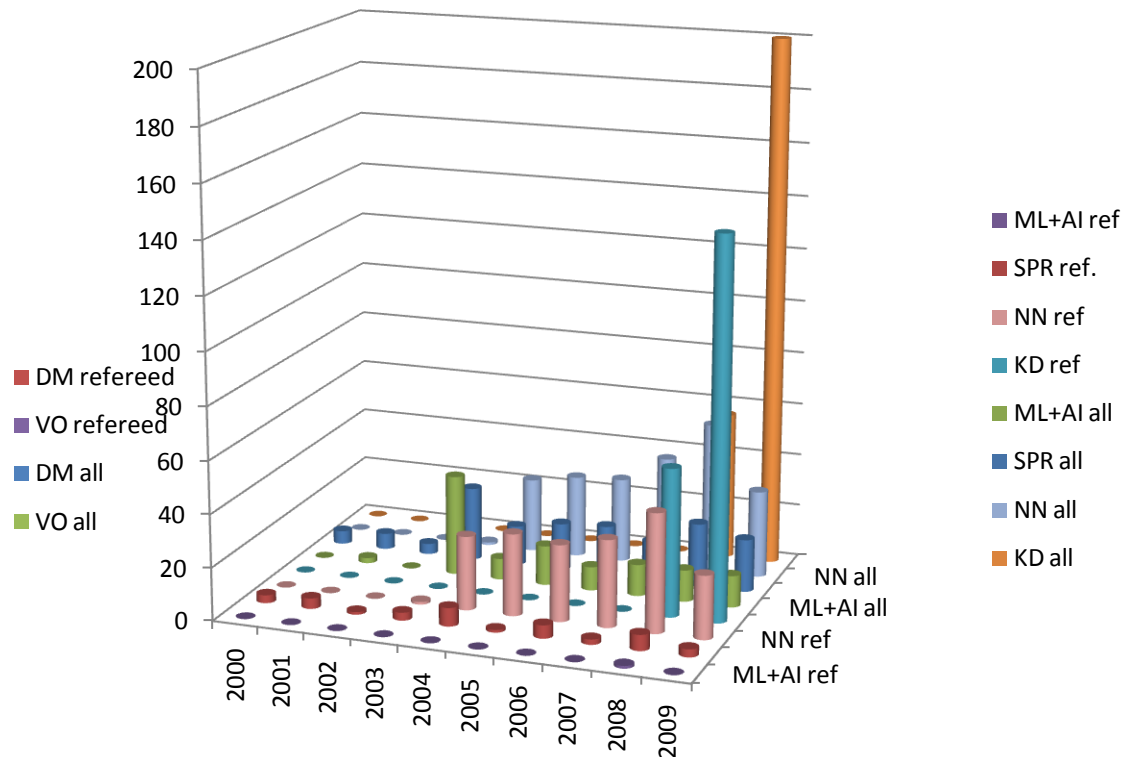
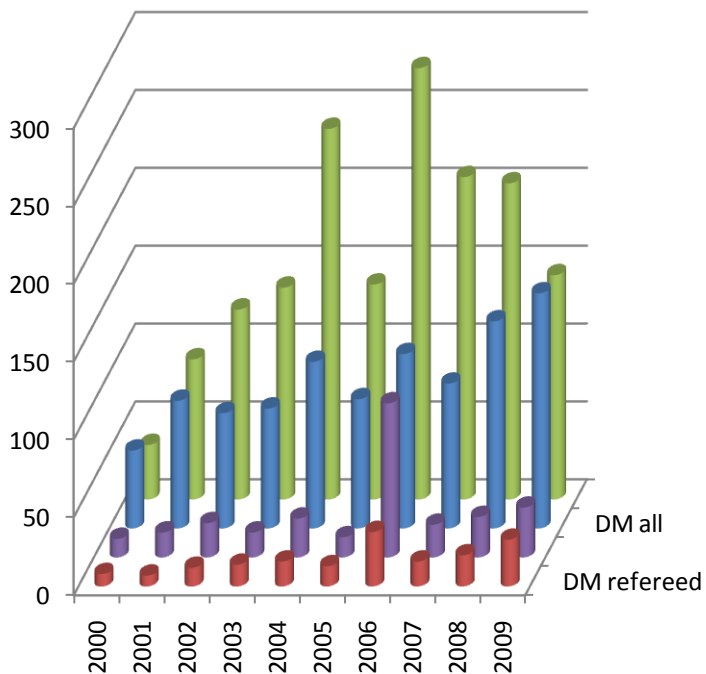


Exposed to a wide choice of algorithms to solve a problem, the r.m.s. astronomer usually panics and is not willing to make an effort to learn them

The r.m.s astronomer doesn't want to become a computer scientist or a mathematician (large survey projects overcome the problem)

Tools must run without knowledge of GRID/Cloud no personal certificates, no deep understanding of the DM tool etc.)





1. Number of technical/algorithmic papers increases with new funding opportunities. Number of refereed papers remains constant.
2. Most of the work, so far, remains at the implementation stage (computer Science and algorithm development) and does not enter the “science production” stage...
3. Out of one thousand papers checked (galaxies, observational cosmology, survey) over the last two years: DM could be applied or involved in at least 30% of them leading to better results

Recent past

Now

Near Future

Separated archives and data centers
(few TB)

Federated archives and data centers
(10 – 100 Tbyte)

Virtual Observatory, LSST, SKA
(1-1000 Pbyte)

No common standards (*.fits)

Common standards (*.fits, *.vot, etc.)

Common standards (*.fits, *.vot, etc.)

Little bandwidth (10/50 Kb s⁻¹)

Larger bandwidth (100-1000 Kb s⁻¹)
(last mile problem)

Larger bandwidth (> 1-10 Gb s⁻¹)

Single CPU processing

Still single CPU processing

GRID/Cloud computing/Multicore

Research praxis

Few objects , few information
(parameter space ~ 10 features)

Many objects , much information
(parameter space > 100 features)

Whole sky, multi-λ, multi epoch catalogues
(parameter space > 100 features)

Traditional statistics

Multi variate statistics

Statistical Pattern Recognition (DM and ML)

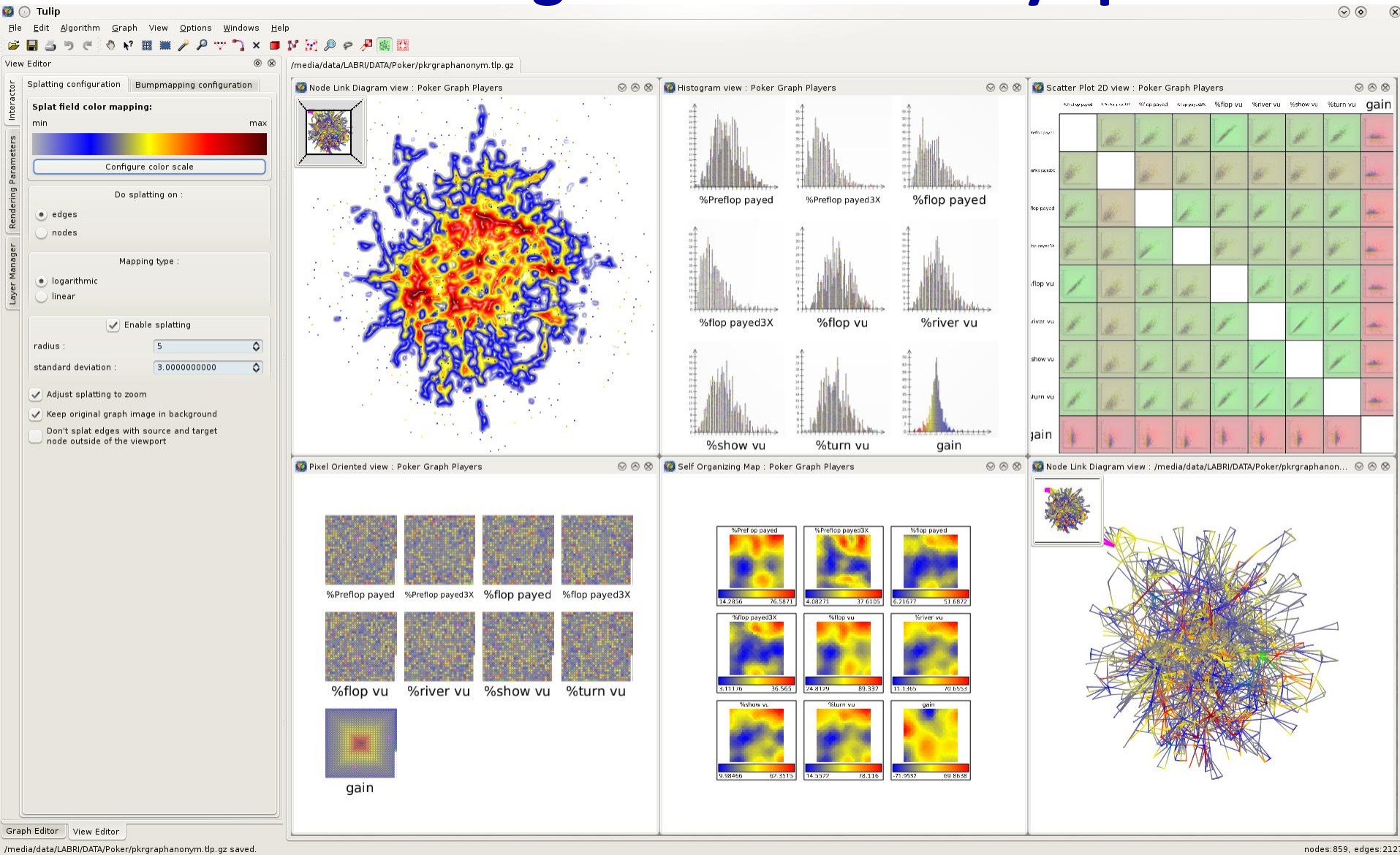
This is only a part of the game
(size and not complexity driven)

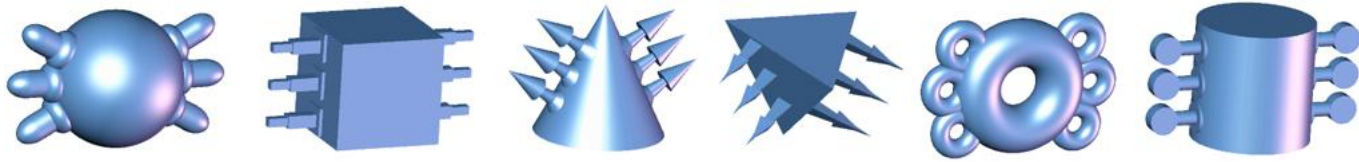


Future developments and some conclusions

- **Better visualization tools for high dimensionality data**
- More machine learning methods
- Parallelization of some codes

Visualization of high dimensionality spaces

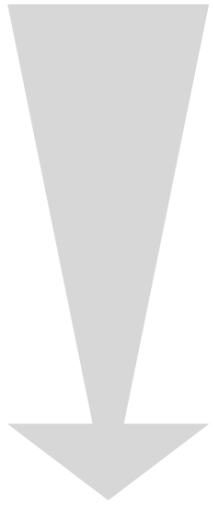




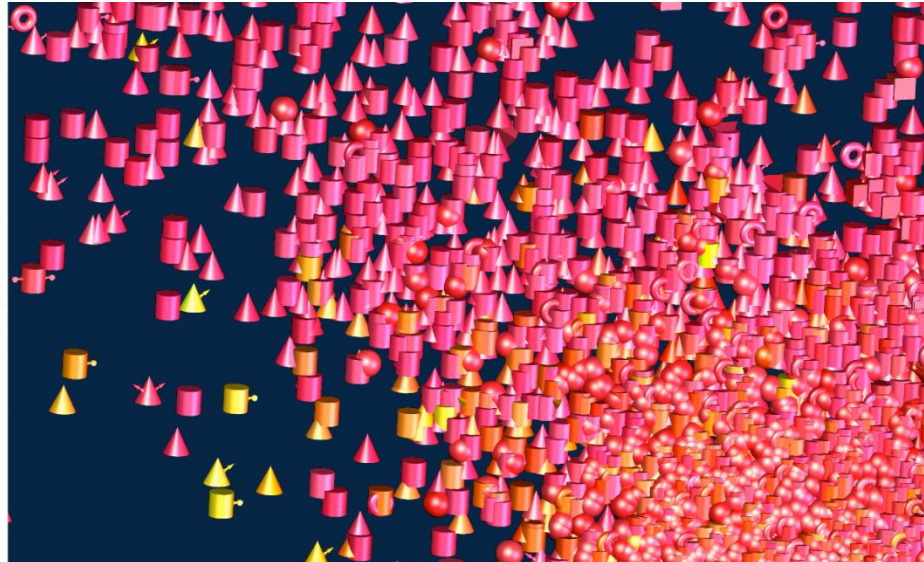
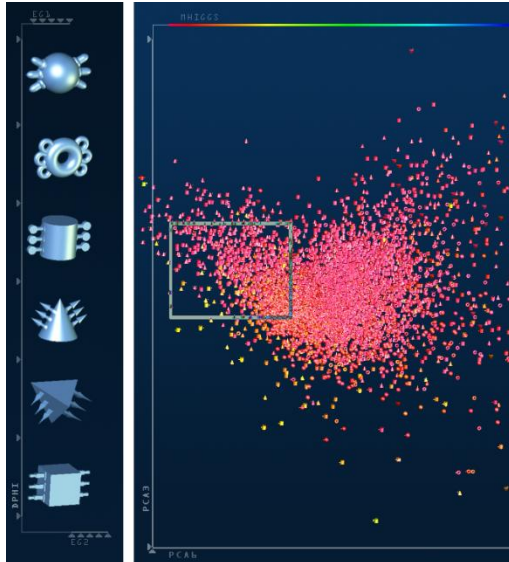
(read order)

(attribute)

- 1,2
- 3
- 4
- 5
- 6
- ...



position (x,y)
shape
hue
left features
right features }
vibration, sound, etc...



Useful links

DAME: <http://voneural.na.inf.it/>

IVOA: <http://www.ivoa.org/>

MICA (Meta Institute for Computational Astrophysics) in Second Life:
<http://www.mica.org/>

<http://www.mica.org/>



MICA Amphitheater



Thanks